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GUJARAT TECHNOLOGICAL UNIVERSITY BE_SEMESTER_VII (NEW) EXAMINATION _ WINTER 2020

DE- SEMESTER-VII (NEW) EAR	WIINATION - WINTER 2020
Subject Code:2172009	Date:28/01/2021

Subject Maine.Soft Combuting Abbileauon	Subject	Name:Soft	Computing	Applications
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Time: 10:30 AM TO 12:30 PM	Total Marks: 56
Time: 10:30 ANT TO 12:30 FM	TOTAL MATES: 50

Instructions:

- 1. Attempt any FOUR questions out of EIGHT questions.
- 2. Make suitable assumptions wherever necessary.
- 3. Figures to the right indicate full marks.

			MARK
Q.1	(a) (b) (c)	With the suitable example define & explain the supervised learning method. With the suitable example define & explain the unsupervised and learning method. Define Soft Computing. Explain its importance. How is Soft Computing different from Hard Computing?	03 04 07
Q.2	(a)	List advantages of Mamdani Method.	03
	(b)	List advantages of Sugeno Method.	04
	(c)	State and explain various methods of de-fuzzification.	07
Q.3	(a)	Define uncertainty and vagueness. Explain concept of fuzziness and membership function.	03
	(b)	Differentiate between classical relations vs Fuzzy relation.	04
	(c)	Explain Noise cancellation using neural networks.	07
Q.4	(a)	Define the Cartesian product of two fuzzy sets with the help of an example.	03
	(b)	What is artificial neural network? Draw the architecture of basic neural network.	04
	(c)	Explain Mc Culloch and Pitt's model.	07
Q.5	(a)	Give the advantages of Neural Network.	03
	(b)	Discuss about the Demorgan's law for the fuzzy sets. Say whether it is similar to	04
	(c)	that of classical sets. Explain Applications of fuzzy logic in control & automation.	07
Q.6	(a)	Define fuzzy inference system. Draw its working diagram.	03
	(b)	Explain the difference between randomness and fuzziness.	04
	(c)	Explain Trajectory prediction using neural networks.	07
Q.7	(a)	Write short on NETTALK.	03
	(b)	Write short note on MEDALINE.	04
	(c)	Explain Fuzzy based robot navigation.	07
Q.8	(a)	Explain concept of Adaptive Resonance Theory.	03
	(b)	Write short note on ADALINE	04
	(c)	Explain neural network in robot navigation.	07

