

**GUJARAT TECHNOLOGICAL UNIVERSITY**

**BE- SEMESTER-V (NEW) EXAMINATION – WINTER 2020**

**Subject Code: 2150909**

**Date: 22/01/2021**

**Subject Name: Control System Engineering**

**Time: 10:30 AM TO 12:30 PM**

**Total Marks: 56**

**Instructions:**

1. Attempt any **FOUR** questions out of **EIGHT** questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.

- |            |   | MARKS     |
|------------|---|-----------|
| <b>Q.1</b> | (a) Describe the components and variables of biological control system involved in walking in a prescribed direction.                     | <b>03</b> |
|            | (b) Write the difference between open loop and closed loop control system.  | <b>04</b> |
|            | (c) Explain transfer function and write its advantages and disadvantages.   | <b>07</b> |
| <b>Q.2</b> | (a) Name the analogous electrical elements in force-voltage analogy for the elements of mechanical translational system.                  | <b>03</b> |
|            | (b) Can a signal flow graph be drawn for nonlinear system? State Mason's gain formula.  | <b>04</b> |
|            | (c) Reduce the block diagram shown in Figure 1 to a single transfer function $\frac{C(s)}{R(s)}$ using block diagram reduction technique. | <b>07</b> |

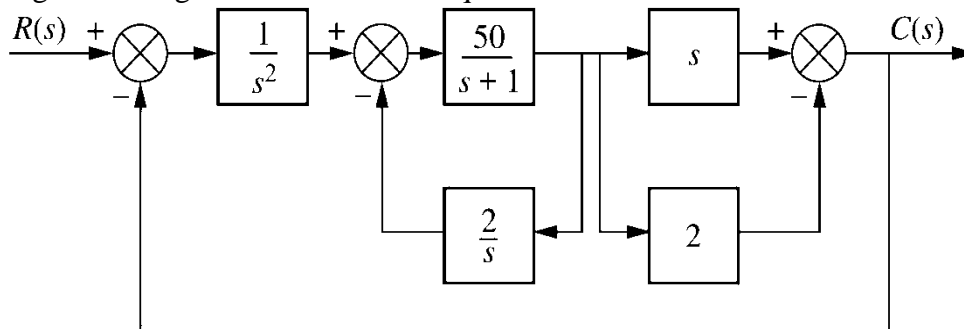


Figure 1

- |   |   |           |
|---|---|-----------|
| <b>Q.3</b>  | (a) Define the following terms<br>1) Delay time 2) Rise time 3) Peak time | <b>03</b> |
|   | (b) Distinguish between type and order of a control system.               | <b>04</b> |
| (c) Find the steady-state errors for inputs of $5u(t)$ , $5tu(t)$ , and $5t^2u(t)$ to the system shown in Figure 3. The function $u(t)$ is the unit step. | <b>07</b>   |           |

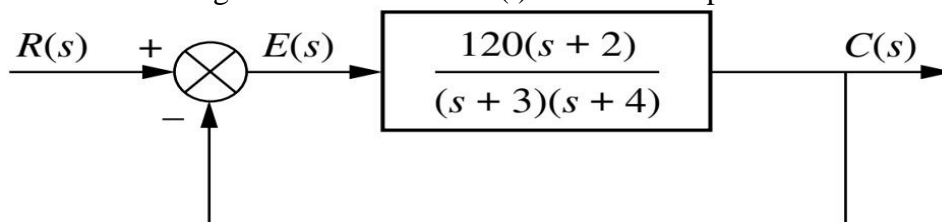


Figure 3

- |            |                                 |           |
|------------|---------------------------------|-----------|
| <b>Q.4</b> | (a) Define the following terms. | <b>03</b> |
|------------|---------------------------------|-----------|

- 1) State 2) State variable 3) State vector
- (b) Explain standard test signals used in control system. **04**
- (c) The closed loop transfer function of unity feedback control system is given by **07**
- $$\frac{C(s)}{R(s)} = \frac{100}{s^2 + 8s + 100}$$
- Determine
- 1) Damping ratio
  - 2) Natural undamped resonance frequency
  - 3) Percentage peak overshoot

- Q.5** (a) What are the conditions to be satisfied for the Root locus to exist at any point in the s-plane? **03**
- (b) Write a short note on the correlation between time and frequency responses. **04**
- (c) For the closed loop transfer function **07**

$$T(s) = \frac{10}{s^8 + s^7 + 12s^6 + 22s^5 + 39s^4 + 59s^3 + 48s^2 + 38s + 20}$$

Check stability of the system. Find how many poles are in the right-half plane?  
Using Routh-Hurwitz stability criterion

- Q.6** (a) What is a Root locus? How can you tell from the Root locus if a system is unstable? **03**
- (b) Explain how do you determine the gain crossover frequency and phase crossover frequency from the Bode plot? **04**
- (c) The unity feedback system has **07**

$$G(s)H(s) = \frac{k}{s(s + 2)(s + 4)}$$

Draw the rough sketch of the Root locus.

- Q.7** (a) Define the Bode plot. What do you mean by an approximate Bode plot? **03**
- (b) Briefly explain about Polar plots. **04**
- (c) Sketch the Bode plots for the transfer function given below: **07**

$$G(s)H(s) = \frac{200}{s(s + 2)(s + 10)}$$

- Q.8** (a) By applying the final-value theorem, find the final value of f(t) whose Laplace transform is given by **03**

$$F(s) = \frac{1}{s(s + 1)}$$

- (b) State Nyquist stability criterion. Why the Nyquist criterion is called a frequency response method? **04**
- (c) Derive Overall transfer function of Field controlled DC motor. **07**

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