www.FirstRanker.com

www.FirstRanker.com

Roll No.						Total No. of Pages: 0	12
						i otal itol oi i agoo i o	

Total No. of Questions: 08

M.Tech. (ME) (2017 Batch) (Sem.-2)
AUTOMATION & ROBOTICS

Subject Code: MTME-206 M.Code: 74982

Time: 3 Hrs. Max. Marks: 100

INSTRUCTIONS TO CANDIDATES:

- 1. Attempt any FIVE questions out of EIGHT question.
- 2. Each question carry TWENTY marks.
- 1. a) What is automation? What it means to us around the world? Describe the basic elements of automation.
 - b) Explain strategies for automation and production systems.
- 2. a) What are the levels of automation? Describe various types of automation based on flexibility.
 - b) Discuss the various types of Directional control valves used in pneumatic systems with neat sketches.
- 3. a) Compare the constructional details and working principle of Pneumatic and Hydraulic Actuators use in robotics. Also, State their relative advantages and disadvantages.
 - b) What do you understand by flexible manufacturing automation? Discuss the salient features of single station manufacturing cell giving an appropriate example.
- 4. a) What is automated assembly system? Explain the following automated assembly systems by their physical configurations:
 - i) Dial-type assembly machine
 - ii) In-line assembly machine
 - iii) Carousel assembly system
 - iv) Single-station assembly machine

1 M-74982 (S9)-2828



- b) What type of material transfer device are used in high volume production system? Also, explain the working of Geneva Mechanism.
- 5. a) Describe the relationship between robotics and automation. Explain with a neat sketch configuration of a robot.
 - b) Explain the following classifications of robots: by power source; by the shape of the work envelope; by the size of the robot; by the weight it can move; by the type of jobs it is optimized for; and by the type of drive system used to move the robot.
- 6. a) Explain any four types of robot programming. Name the important requirements of programming languages.
 - b) Explain the characteristics of various transmission systems used in industrial robotic arm along with their advantages and disadvantages.
- 7. a) Explain architecture of a Programmable logic controller with the help of neat sketch.
 - b) What is the need for feeders in automation systems? How feeders are classified? Explain the criteria for feeder selection and types of feeders used in industry.
- 8. a) Discuss the working of automated storage and retrieval systems for materials handling applications giving various configurations of ASRS systems.
 - b) What is artificial intelligence? Explain the concept of export system and its applications in Robotics.

NOTE: Disclosure of Identity by writing Mobile No. or Making of passing request on any page of Answer Sheet will lead to UMC against the Student.

2 | M-74982 (S9)-2828