## www.FirstRanker.com

## **GUJARAT TECHNOLOGICAL UNIVERSITY**

**BE - SEMESTER- VIII (New) EXAMINATION - WINTER 2019** 

Subject Code: 2181706	Date: 21/11/2019

**Subject Name: Robotic Engineering** 

Time: 02:30 PM TO 05:00 PM	Total Marks: 70
----------------------------	-----------------

## **Instructions:**

1. Attempt all questions.

- 2. Make suitable assumptions wherever necessary.
- 3. Figures to the right indicate full marks.

	3.	rigures to the right indicate run marks.	MARKS
Q.1	(a)	List and state three laws of robotics stated by Isaac Asimov	03
	<b>(b)</b>	Define degree of freedom, robot, repeatability and links	04
	(c)	List and explain in detail 3 criteria used for classification of robot manipulator.	07
Q.2	(a)	Explain Jacobian.	03
	<b>(b)</b>	Explain reach and stroke of robotic manipulator	04
	(c)	Explain in detail different types of robot programming with advantages and examples of each	07
		OR	
	<b>(c)</b>	Discuss pros and cons of applying robots in industrial applications	07
Q.3	(a)	Draw degree of freedom associated with arm	03
	<b>(b)</b>	What points are considered while selecting HP rating of a motor?	04
	<b>(c)</b>	Explain in detail the method used for solving inverse kinematic problem.	07
		OR	0.0
Q.3	(a)	List in detail specifications of an industrial robot.	03
	<b>(b)</b>	Explain in detail hydraulic actuator.	04
	<b>(c)</b>	What are the points to be considered for selecting a robot for a particular	07
0.4	(-)	application? Explain in detail.	02
<b>Q.4</b>	(a)	Explain in detail robot cell.	03 04
	(b)	Explain work envelope with necessary example and figure.  List out various sensors which can be interfaced with robots. Explain any	04 07
	<b>(c)</b>	one sensor interface with robot in detail.	U/
		OR	
Q.4	(a)	List 3 points of difference between electrical and pneumatic actuators	03
<b>~</b> ··	(b)	List different types of grippers	04
	(c)	Explain in detail different types of end effectors.	07
Q.5	(a)	List any 3 types of arms used in industrial robot manipulators	03
	<b>(b)</b>	What do you mean by forward kinematics?	04
	(c)	Explain in detail 2 main configurations of wrist designs	07
		OR	
Q.5	(a)	Explain torque sensor.	03
	<b>(b)</b>	What is Hill climbing technique?	04
	<b>(c)</b>	Explain in detail selection and design a robot for an assembly line where	07
		nainting of car is done in automobile industry	

\*\*\*\*\*