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Subject Code:2142003

Date:15/05/2019

Subject Name: Control Theory Time:02:30 PM TO 05:00 PM

Total Marks: 70

Instructions:

- 1. Attempt all questions.
- 2. Make suitable assumptions wherever necessary.
- 3. Figures to the right indicate full marks.

MARKS

03

07

- Q.1(a) Define: 1) delay time, 2) rise time, 3) pick time.03(b) State the advantages of frequency response of control system.04
 - (c) Give the difference between block diagram and SFG method. 07

Q.2 (a) Derive transfer function of Field controlled D.C. Motor.

- (b) Derive and sketch the time response of 1st order control system for 04 the unit step input.
- (c) Determine the transfer function of the following electric network. 07



(c) Find mathematical model of following system.

Q.3 Explain initial value and final value theorem. 03 **(a)** Explain Force-Voltage analogous system. 04 **(b)** (c) Write a short note on Gear Train and derive all the required equation. 07 OR Q.3 Define Gain crossover frequency. **(a)** 03 Explain Force-Current analogous system. 04 **(b)**

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- **Q.4** 03 (a) Define : 1) state variable, 2) state vector, 3) state space
 - A unity feedback system has $G(s) = \frac{k(s+1)}{s^2(s+2)(s+5)}$. Using Routh-**(b)** 04 Hurwitz criteria find range of k for the closed loop system to be stable.
 - (c) Simplify the block diagram shown in Figure 2. Then; obtain the 07 closed-loop transfer function C(s)/R(s).





- **O.4** (a) Derive expression of K_P, K_V, K_A for Type '0' control system. 03
 - (b) Define thermal resistance and thermal capacitance. Also derive the 04 transfer function of Thermometer placed in water bath as a Thermal system. 07
 - For the system having the open loop transfer function (c)

$$G(s)H(s) = \frac{10}{s(s+1)(s+10)}$$

Determine the stability of the system by plotting the Bode plot of the system.

- (a) Define and explain following terms with respect to frequency Q.5 03 response (i) Gain Margin (ii) Phase Margin (iii) Stability
 - **(b)** Write advantages and disadvantages of nyquist plot.
 - (c) A feedback control system has open loop transfer function 07

$$G(s)H(s) = \frac{\kappa}{s(s+4)(s^2+4s+20)}$$

subjects for K= 0 to ∞ indicate all point on the second seco

Plot the root locus for K=0 to ∞ . Indicate all point on it.

Q.5 **(a)** Explain with suitable example, one method for linearization of 03 nonlinear mathematical model.

04



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 - Explain constant-M circles and constant-N circles by deriving related 07 (c) expressions. Explain how resonant peak can be obtained.

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