

# GUJARAT TECHNOLOGICAL UNIVERSITY

BE - SEMESTER-VI(NEW) – EXAMINATION – SUMMER 2019

**Subject Code:2160703**

**Date:21/05/2019**

**Subject Name:Computer Graphics**

**Time:10:30 AM TO 01:00 PM**

**Total Marks: 70**

**Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks. ]

		MARKS
<b>Q.1</b>	(a) Write a difference between Raster scan system and Random scan system.	<b>03</b>
	(b) Explain shadow mask method in detail.	<b>04</b>
	(c) Derive all formulas for bresenham's line drawing algorithm. Write an algorithm for bresenham's line drawing algorithm.	<b>07</b>
<b>Q.2</b>	(a) Write limitations of DDA line drawing method.	<b>03</b>
	(b) Write a note on Even-Odd rule.	<b>04</b>
	(c) Explain midpoint ellipse drawing algorithm with example.	<b>07</b>
	<b>OR</b>	
	(c) Explain scan line fill algorithm with all data structures.	<b>07</b>
<b>Q.3</b>	(a) Explain the term region codes.	<b>03</b>
	(b) Derive 2D transformation matrix for rotation.	<b>04</b>
	(c) Explain 2D transformation for reflection about arbitrary line.	<b>07</b>
	<b>OR</b>	
<b>Q.3</b>	(a) Write a note on 2D shearing.	<b>03</b>
	(b) The reflection along line $Y=X$ is equivalent to reflection along x-axis followed by counter clockwise rotation by angle $\phi$ . Find the value of $\phi$ .	<b>04</b>
	(c) Explain the Nicholl-Lee-Nicholl(NLN) Line Clipping algorithm in detail.	<b>07</b>
<b>Q.4</b>	(a) Compare interpolation spline and approximate spline.	<b>03</b>
	(b) Rotate a triangle XYZ with vertices A(2,2,2),B(3,4,7) and C(8,9,12) about Y-axis in clockwise direction by angle 90 degree.	<b>04</b>
	(c) Explain Bezier curve properties.	<b>07</b>
	<b>OR</b>	
<b>Q.4</b>	(a) What is projection? List out various types of projection.	<b>03</b>
	(b) Explain parametric and geometric continuity.	<b>04</b>
	(c) Derive transformation matrix for 3D rotation about arbitrary line.	<b>07</b>
<b>Q.5</b>	(a) Explain YIQ color model.	<b>03</b>
	(b) Derive a perspective projection of a point P(x,y,z) on a view plane positioned at $z=0$ and center of projection is on negative z-axis at distance d.	<b>04</b>
	(c) What is depth buffer method? Explain depth buffer algorithm with example.	<b>07</b>
	<b>OR</b>	
<b>Q.5</b>	(a) Explain the term hue and saturation.	<b>03</b>
	(b) Write a note on 3D reflection.	<b>04</b>
	(c) Briefly explain back face detection algorithm.	<b>07</b>

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