	Seat	Ranker.com Enrolment No	_
Fi	rstran	ker's GUJARAT TECHNOLOGICAL UNIVERSITY BE - SEMESTER-VI(NEW) - EXAMINATION - SUMMER 2019	
	Subj	ect Code:2162404 Date:10/05/2019	
	Subi	ect Name:Industrial Drives & Control-I	
	Time	:10:30 AM TO 01:00 PM Total Marks: 70	
	Instru	ctions:	
		1. Attempt all questions.	
		2. Make suitable assumptions wherever necessary.	
		1. Figures to the right indicate full marks.	
() 1 (a	Define Electric Motor Drive and Draw block diagram of Electric Motor Drives	03
(2.1 (a (h	b) List the comparisons between Active and Passive Load Torque	03
	(U (C	Derive torque equation of DC Motor indicating Dynamic of Electric Drive	07
()) (a	Define Group Drive Individual Drive and Multi-motor Drive	07
	2.2 (a (h) List the different types of Speed Control of DC Motor Explain any one with	03
	(10	necessary diagram and equations	U-T
	(6	Draw and explain mathematical model of armature controlled DC drive	07
	(OR	07
	(c	List the types of Duty in Electrical Motor Drive and Explain each in brief.	07
().3 (a	Draw Circuit diagram and characteristics of Chopper circuit for braking control.	03
	(b) Explain the comparisons between: Field and Armature Control of DC Motor.	04
	(c	Explain the two quadrant operation of Chopper Controlled separately excited DC	07
	,	motor with suitable diagram.	
		OR	
(Q.3 (a) Draw and Explain Static Ward Leonard System.	03
	(b) Explain the comparisons between: Constant Torque and Constant HP Operation.	04
	(c	e) Explain closed loop control scheme of separately excited DC motor for control	07
		of below & above base speed.	
(Q.4 (a	Why PI Control is very important in closed loop DC drive system?	03
	(b) Explain the difference between: Circulating & Non Circulating mode of dual	04
		converter operation.	
	(C	e) Write technical short note on: PLL Based DC Drive.	07
		OR	
(Q.4 (a	Draw and explain the field current reversible drive.	03
	(b) Explain the comparisons between In phase and phase shifted mode of multiphase	04
		chopper.	
	(0	block diagram & necessary flow chart explain working of microcomputer	07
		control of DC Drives.	0.2
(2. 5 (a	Draw and Explain requirement of servo motor drives.	03
	(D)	b) Draw and explain block diagram of Permanent Magnet DC Motor Drives.	04
	(0	excited motors	0/
ſ) 5 (n) Explain the selection of drive for speed reversal	63
	2.2 (a (h	Why Current loop in to be introduced as an inner loop in closed loop operation?	03
	(U	Explain with necessary comments	UT
	(6	Define Stability of motor load combination Explain criteria for steady state	07
	, c	stability for using seven possible combination of speed and torque curve of motor	57
		and load.	
