

**GUJARAT TECHNOLOGICAL UNIVERSITY****BE - SEMESTER-VII(NEW) EXAMINATION – SUMMER 2019****Subject Code:2170203****Date:10/05/2019****Subject Name:Vehicle Dynamics****Time:02:30 PM TO 05:00 PM****Total Marks: 70****Instructions:**

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.

**MARKS**

<b>Q.1</b>	(a) Define (i) Lift (ii) Drag.	<b>03</b>
	(b) Explain SAE Vehicle axis.	<b>04</b>
	(c) Derive an equation to calculate the dynamic axial load for the following condition (i) Vehicle is on ground (ii) Vehicle is in low speed acceleration (iii) vehicle is on grade.	<b>07</b>
<b>Q.2</b>	(a) Define (i) Slip angle (ii) Camber thrust.	<b>03</b>
	(b) Describe about aerodynamic aids.	<b>04</b>
	(c) Classify types of tyres with neat sketch along with their advantages and disadvantages.	<b>07</b>
	<b>OR</b>	
	(c) Define rolling resistance. Explain factors affecting rolling resistance.	<b>07</b>
<b>Q.3</b>	(a) Define active suspension.	<b>03</b>
	(b) Explain anti-dive suspension geometry.	<b>04</b>
	(c) Illustrate about roll center analysis.	<b>07</b>
	<b>OR</b>	
<b>Q.3</b>	(a) Justify need of suspension system.	<b>03</b>
	(b) Distinguish independent suspension and dependent suspension.	<b>04</b>
	(c) Classify types of suspension systems along with pro and cons of each.	<b>07</b>
<b>Q.4</b>	(a) Explain height of motorcycles center of gravity.	<b>03</b>
	(b) Define wheelbase and steering axis angle of motorcycle.	<b>04</b>
	(c) Explain Quasi-static rollover of a rigid vehicle.	<b>07</b>
	<b>OR</b>	
<b>Q.4</b>	(a) Justify importance of trail.	<b>03</b>
	(b) Define fork offset and wheel flop of motorcycle.	<b>04</b>
	(c) Explain Quasi-static rollover of a suspended vehicle.	<b>07</b>
<b>Q.5</b>	(a) Define (i) Camber (ii) Under steer (iii) Over steer	<b>03</b>
	(b) Differentiate between steering system used in front wheel drive system and steering system used in rear wheel drive vehicle.	<b>04</b>
	(c) Justify need of steering system. Explain steering geometry errors.	<b>07</b>
	<b>OR</b>	
<b>Q.5</b>	(a) Define (i) Caster (ii) Neutral steer (iii) Wheelbase	<b>03</b>
	(b) Explain four wheel steering system.	<b>04</b>
	(c) Explain steering system forces and moments.	<b>07</b>

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