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GUJARAT TECHNOLOGICAL UNIVERSITY

BE - SEMESTER-VII(OLD) • EXAMINATION - WINTER 2017

Subject Code: Computer Aided Manufacturing Date:18/11/2017

Subject Name: 172501

Time: 10.30 AM TO 01.00 PM Total Marks: 70

Instructions:

- 1. Attempt all questions.
- 2. Make suitable assumptions wherever necessary.

from conventional manufacturing stages?

- 3. Figures to the right indicate full marks.
- 4. Support your answers by neat sketches wherever necessary.
- 5. Use of G codes & M codes provided by GTU is permitted.
- Q.1 (a) Write advantages & disadvantages of CNC machines.
 (b) Explain various stages involved with NC manufacturing. How do they differ
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 07
- Q.2 (a) Explain with neat sketches the following: 07
 - (i) Machine zero
 (ii) Program zero
 (iii) Part zero
 (b) Name different punch tape readers & explain any two of them.
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- (b) Explain briefly the constructional features ball screw with neat sketches & state its application.
- Q.3 (a) Explain Do loop and Macro facilities of programming with suitable examples.
 (b) The figure -1 shows the dimensions of a finished component to be made from a
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 - (b) The figure -1shows the dimensions of a finished component to be made from a bar of Ø80 mm X 135 mm. Write the manual part programme to machine the component using G90 canned cycle. Refer to Table -1 for G-codes & M-codes. Use following process plan:

Operation No.	Operation	Tool No.	Cutting Speed (m/min)	Feed Rate (mm/rev)	Depth of Cut (mm)
10	Facing	01	160	0.15	-
20	Rough turning	03	200	0.20	4 (max.)
30	Finish turning	03	200	0.15	1.5(max.)

OR

- Q.3 (a) What is Automated Guided Vehicles? Explain different types of AGVs with their advantages and limitations.
 - (b) Prepare the process plan & write manual part programme for profile milling of the part shown in figure -2. Assume the plate thickness to be 10 mm. Refer to Table -1 for G-codes & M-codes.
- Q.4 (a) What are different types of computer aided process planning? Explain with 07 suitable examples.
 - (b) Write short notes on: (i) Robot sensors & (ii) End-effectors in robots.

OR

- Q.4 (a) Give advantages, limitations and applications of flexible manufacturing system. 07
 - **(b)** What is group technology? Explain benefits of GT. **07**
- Q.5 (a) What is meant by adaptive control? Explain all types of adaptive control. 07
 - (b) Write short note on "Selective Laser Sintering" technique of rapid prototyping. 07

Q.5 (a) Define Mechatronics. Discuss various elements of mechatronics. 07



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First(b) k What is part family? Explain risker Election and coding springer af Represon 07 technology.

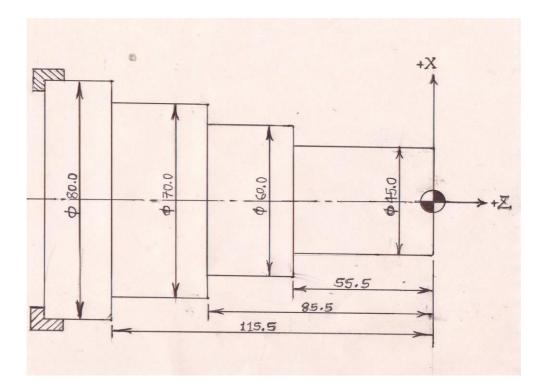


Figure – 1 [Q.3 (b)]

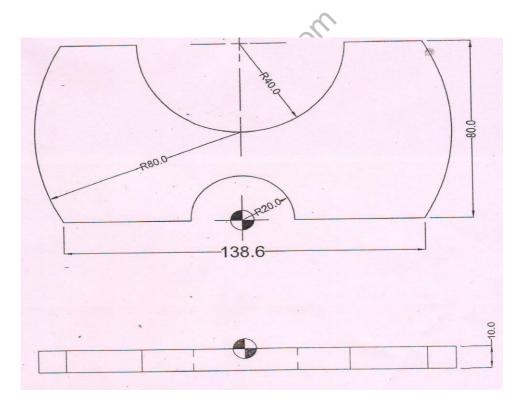


Figure - 2 [OR Q.3 (b)]

Table -1



Firstra	Firstranker's choice NC/CNGwMourristRanker.com					
Tu	rning Center FANUC OT Controller	Macl	Machining Center FANUC OM Controller			
G00 Positioning in Rapid		G00	Positioning in Rapid			
G01	Linear Interpolation	G01	Linear Interpolation			
G02	Circular Interpolation (CW)	G02	Circular Interpolation (CW)			
G03	Circular Interpolation (CCW)	G03	Circular Interpolation (CCW)			
G04	Dwell	G04	Dwell			
G20	Inch Units Programming	G17	XY Plane			
G21	Metric Units Programming	G18	XZ Plane			
G28	Automatic return to reference point	G19	YZ Plane			
G29	Automatic return from reference point	G20	Inch Units Programming			
G40	Cutter compensation Cancel	G21	Metric Units Programming			
G41	Cutter compensation Left	G28	Automatic return to reference point			
G42	Cutter compensation Right	G29	Return from Zero Return Position			
G43	Tool Length Compensation (Plus)	G40	Cutter compensation Cancel			
G44	Tool Length Compensation (Minus)	G41	Cutter compensation Left			
G49	Tool Length Compensation Cancel	G42	Cutter compensation Right			
G50	Maximum spindle speed in rpm	G43	Tool Length Compensation (Plus)			
G96	Constant surface speed ON	G44	Tool Length Compensation (Minus)			
G97	Constant surface speed OFF	G49	Tool Length Compensation Cancel			
G98	Feed rate, per min	G90	Absolute Positioning/ Programming			
G99	Feed rate, per rev.	G91	Incremental Positioning/ Programming			
		G94	Feed rate, per min			
		G95	Feed rate, per rev.			
		G98	Return to initial point level			
		G99	Return to R point level			
	Canned Cycles		Canned Cycles			
G90	Single Pass Turning Cycle	G73	High Speed Peck Drilling Cycle			
G92	Single Pass Threading Cycle	G74	Left hand Tapping Cycle			
G94	Single Pass Facing Cycle	G76	Fine Boring Cycle			
G70	Finishing Cycle	G80	Cancel Canned Cycles			
G71	Turning Cycle	G81	Spot Drilling Cycle			
G71	Multi-pass Rough Turning Cycle	G82	Counter Boring Cycle			
G72	Multi-Pass Rough Facing Cycle	G83	Deep Hole Peck Drilling Cycle			
G73	Pattern Repeating	G84	Right hand Tapping cycle			
G74	Grooving in Z-axis	G85	Boring Cycle			
G75	Grooving in X-axis					
G76	Multi-Pass Thread Cutting					
Miscellaneous Codes						
M00	Program Stop	M06	Tool Change			
M01	Optional Program Stop	M98	Subprogram Call			
M02	Reset	M99	Subprogram End			
M03	Spindle On/start Clockwise	M70	Mirror On – X			
M04	Spindle On/start Counterclockwise	M71	Mirror On – Y			
M05	Spindle Stop	M80	Mirror Off – X			
M08	Coolant On	M81	Mirror Off – Y			
M09	Coolant Off	M30	Program End & Rewind			
M30	Program End & Rewind	M00	 same as Turning Center codes 			
		to				
		M09				