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GUJARAT TECHNOLOGICAL UNIVERSITY

BE - SEMESTER-VIII (NEW) EXAMINATION - WINTER 2017

Subject Code: 2180807	Date: 02/11/2017
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Subject Name: Industrial Automation

Time:02:30 PM TO 05:00 PM	Total Marks: 70

Instructions:

1.	Attempt a	all questions.	

		Make suitable assumptions wherever necessary.				
	3.	Figures to the right indicate full marks.	MARKS			
0.1	()					
Q.1	(a)	<u> </u>	03			
	(b)	(1) Variable Range (2) Neutral Zone (3) Control Lag Define following Process characteristics:	04			
	(6)	(1) Process Equation (2) Process Lag	04			
	(c)	What is an Industrial Automation? Explain generalized automation and	07			
	(0)	production systems and their classification.	· ·			
Q.2	(a)	State the Advantages, Disadvantages and Applications of Industrial	03			
	` '	Automation.				
	(b)	Explain the concept of Production system with its Block diagram.	04			
	(c)	Explain Direct Digital Control in detail with suitable diagram.	07			
		OR				
	(c)	Explain Supervisory Control in detail with suitable diagram.	07			
Q.3	(a)		03			
	(3.)	(1) Error (2) Dead Time (3) Cycling	0.4			
	(b)	Explain following discontinuous controller modes	04			
	(c)	(i)Two position mode (ii) Multi position mode Explain PI Controller with suitable application.	07			
	(0)	OR	07			
Q.3	(a)		03			
C	(b)		04			
	(c)	Explain the Proportional Integral Derivative (PID) controller mode with	07			
		suitable example.				
Q.4	(a)	Explain ladder diagram elements.	03			
	(b)	Discuss relative merits & demerits of PLC & DCS.	04			
	(c)	Explain various types of I/O Modules and Explain the Layout of I/O separately connected to PI C	07			
connected to PLC OR						
Q.4	(a)	Block diagram of PLC.	03			
	(b)	Discuss briefly about Intelligent Controllers.	04			
	(c)	Explain the block diagram of distributed control system (DCS).	07			
Q.5	(a)	Explain Application, Advantage and Disadvantage of Hydraulic system	03			
	(b)	Explain Pneumatic control System.	04			
	(c)	Explain SCADA with suitable diagram.	07			
	OR					
Q.5	(a)	Give the Introduction about CNC machine.	03			
	(b)	An integral controller is used for speed control with a set point of 12 rpm	04			
		within a range of 10 to 15 rpm. The controller output is 22% initially.				
		The constant $Ki = -0.15\%$ controller output per second per percentage				
		error. If the speed jumps to 13.5 rpm, Calculate the controller output after				
	(c)	2 sec for a constant ep. Develop ladder diagram for Traffic Control Signals.	07			
	(0)	Develop ladder diagram for Traffic Control Signals.	07			

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