



Q.5

control circuit.

GUJARAT TECHNOLOGICAL UNIVERSITY BE SEMESTER-VIII(OLD) • EXAMINATION – WINTER 2017

•			Date: 02-11-2017	
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Q.1	(a) (b)	Explain resolvers and magnetic pickups as a encoder. List out selection criteria for dc motor for incremental motion applications.	07 07	
Q.2	(a) (b)	Explain permanent magnet moving coil dc motor. Explain the techniques for minimizing torsional resonance effect in detail.	07 07	
	(b)	OR List out all methods of speed control of dc motor and explain any one in detail.	07	
Q.3	(a) (b)	Write a short note on unidirectional servo amplifier. Explain bipolar PWM amplifiers.	07 07	
Q.3	(a) (b)	OR Draw and explain velocity control system with block diagram. Write short not on phase locked servo system.	07 07	
Q.4	(a) (b)	Describe the hybrid type step motor with relevant waveform/diagram. List out the selection criteria for stepper motor. Explain step angle resolution and torque requirements. OR	07 07	
Q.4	(a)	What are the advantages and disadvantages of step motors? Explain the step motor performance characteristics in detail.	07	
	(b)	Explain any two application of step motor.	07	
Q.5	(a) (b)	Explain any one suppression circuit for DC motor control with diagram. Explain effect of lead angle in closed loop control of step motor. OR	07 07	

Why over drive circuits are required for step motors? Explain dual voltage

sequencer circuit with waveform of output phase for each pulses.

Draw and explain bidirectional four-phase single and two phase on logic

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