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GUJARAT TECHNOLOGICAL UNIVERSITY

Subje Subje Time:	B ct Co ct Na 10:3	BE - SEMESTER-VII (NEW) EXAMINATION - WINTER 2017 ode: 2170914 Date:0 ome: Digital Signal Processing(Departmental Elective - 1 60 AM TO 01:00 PM Total	2/11/2017 (I) Marks: 70
Instruc	tions: 1. A 2. M 1. Fi	ttempt all questions. Take suitable assumptions wherever necessary. gures to the right indicate full marks.	
			MARKS
Q.1	(a) (b)	Differentiate: Analog and digital signal processing. Define 1) Signal 2) System 3) Sampling (4) Quantization Give example of each.	03 04
	(c)	What is pipelining? Explain with reference to DSP. What is interlocking? State need of interlocking in brief.	07
Q.2	(a)	What is ROC in z transform? What is its importance?	03
	(b)	Discuss interconnection of LTI systems.	04
	(c)	State and prove the relationship between z-transform and discrete time Fourier transform.	07
		State and prove properties of Equipier transform	07
Q.3	(c) (a)	Explain the following terms with respect to Digital Signal Processor: 1) MAC	07 03
	(b)	Explain DIT algorithm.	04
	(c)	State and prove Parseval's relation for DTFT. OR	07
Q.3	(a)	Draw the block diagram of basic generic harward architecture for a Signal processor	03
	(b)	Define the following terms:	04
	(c)	1) Impulse Response 2) Convolution 3) Correlation 4) Aliasing State basic structures of IIR systems. Also explain realization of direct form I structure.	07
Q.4	(a)	Determine which of following signal is periodic. (1) $x_1(t) = \sin 10\pi t$ (2) $x_2(t) = \sin 3\pi t$	03
	(b) (c)	Explain General Application of DSP. Define cross correlation and auto correlation. Find out correlation of sequences. $X(n)=\{2, 1, 3, 7, 1, 2, -3\}, y(n)=\{1, -1, 2, -2, 4, 1, -2, 5\}$	04 07
04		UR (1) Determine the z transform of the signal	02
Q.4	(a)	$x(n) = \delta(n+1) + 6\delta(n) + 12\delta(n-3) - \delta(n-4)$	US
	(b)	Find the convolution of $x(n) = (e)^{(-n_2)}$ and $h(n) = 3n_2$ for all n.	04
	(c)	Write short note on: Hilbert Transform.	07
Q.5	(a)	State Properties of DFT	03
	(b)	State and prove Final Value theorem for Z-transform	04



irstran	K(E) -	Explain the structures for FirstRanker EB systems. OR	www.FirstRankeP.7	com
Q.5	(a)	For the system described by $y(t) = x(2t)$, determine why system is	ether the 03)
	(b)	(i) Stable (ii) causal Find the Z-transform and ROC of x (n) = $(a)^n u(n)$.	04	ļ

(c) Discuss the concept of zero input limit cycle oscillation. How this 07 can be eliminated?

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