

- Why the ROC of Z-transform can not contain any pole?
- Determine whether the system is linear or non-linear  $y(n) = 2x(n) + 3u(n - 3)$ .
- Give the relation between Z-transform and discrete time Fourier transform (DTFT).
- Find the z-transform of the signal  $x(n) = \delta(n-3)$ .
- What are the three quantization errors due to finite word length registers in digital filters?
- Give the advantages of digital filter over analog filter.
- What are the limitations of impulse invariant method?
- How the order of the filter affects the frequency response of Chebyshev filter?
- What is instruction pipelining? Briefly explain the pipeline operation.
- What are the advantages of DSP processors over conventional processors?

**SECTION-B**

2. With an example, discuss in detail time invariance and causality for a discrete-time system.
3. Compute the convolution  $y(n)$  of  $x(n) = \{1, -2, 3, -4, 5\}$  and  $h(n) = \{1, 1, -2\}$ .
4. What is DITFFT algorithm? Give the computation efficiency of FFT over DFT.
5. Determine output response  $y(n)$  of the FIR filter using overlap add method for  
 $x(n) = [3, 0, -2, 0, 2, 1, 0, -2, -1, 0]$  and  $h(n) = [2, 2, 1]$
6. With the help of a block diagram, explain the architecture of a TMS processor.

**SECTION-C**

7. Determine the direct Forms I and II realizations for second-order filter given by :  
$$y(n) = 2b \cos \omega_0 y(n-1) - b^2 y(n-2) + x(n) - b \cos \omega_0 x(n-1)$$
8. Obtain the mapping formula and discuss the stability for bilinear transformation technique. Apply bilinear transformation to

$$H(s) = \frac{2}{(s+1)(s+5)}$$

With  $T = 0.1$  s.

9. Write short notes on :
  - a) One sided Z-transform
  - b) Quantization of filter coefficients

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