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Total No. of Pages : 02

Total No. of Questions : 09

B.Tech.(EE) PT (Sem.-8) NON LINEAR AND DIGITAL CONTROL SYSTEMS Subject Code : BTEE-603 M.Code : 74388

Time: 3 Hrs.

Max. Marks: 60

INSTRUCTIONS TO CANDIDATES :

- 1. SECTION-A is COMPULSORY consisting of TEN questions carrying TWO marks each.
- 2. SECTION-B contains FIVE questions carrying FIVE marks each and students have to attempt any FOUR questions.
- 3. SECTION-C contains THREE questions carrying TEN marks each and students have to attempt any TWO questions.

SECTION-A

1. Answer briefly :

- a) What are advantages of state space representation of a control system?
- b) What do you mean by observability of a control system ?
- c) Mention some of the limitations of describing functions.
- d) What is backlash nonlinearity?
- e) What are the requirements for a function to be valid Lyapunov function?
- f) What is Z-transform of $x(n) = \{1,0,1\}$
- g) Define pulse transfer function.
- h) What is aliasing of a signal?
- i) What do you mean by first order hold ?
- j) For what Routh-Hurwitz criterion is used in discrete time systems?



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SECTION-B

- 2. Obtain a general solution for state variable model.
- 3. Draw phase portrait for the following system.

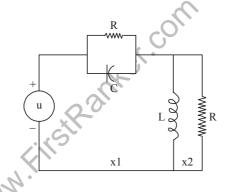
$$\dot{x}_1 = 2x_1 + x_2$$

 $\dot{x}_2 = 2x_1 - x_2$

- 4. Discuss variable gradient method for construction of Lyapunov function V(X).
- 5. Discuss method of isoclines.
- 6. Discuss Lyapunov direct method for stability analysis.

SECTION-C

- 7. Derive an expression for describing function for a relay with dead-zone nonlinearity.
- 8. a) Consider the following circuit. Derive its state space representation.



- b) Comment on controllability and observability of the circuit shown in figure above.
- 9. Using Jury's test, comment upon the stability of a discrete time control system with following characteristic equation.

$$P(z) = z^4 - 1.2z^3 + 0.07z^2 + 0.3z - 0.08 = 0$$

NOTE : Disclosure of Identity by writing Mobile No. or Making of passing request on any page of Answer Sheet will lead to UMC against the Student.