

Rajiv Gandhi University of Health Sciences, Karnataka

Second Year Bachelor in Prosthetics and Orthotics Degree Examination – OCT-2019
Time: Three Hours

Max. Marks: 80 Marks

PROSTHETICS SCIENCE - II (RS3) O.P. CODE: 2974

Your answers should be specific to the questions asked Draw neat, labeled diagrams wherever necessary

ESSAYS TYPE (Answer any Two)

2 x 10 = 20 Marks

- Define alignment? Explain the Bench & Static alignment of trans femoral prosthesis.
- Explain the different types of prosthetic knee joints.
- Explain the checkout process of Knee disarticulation prosthesis.

SHORT ESSAYS TYPE (Answer any Six)

6 X 5 = 30 Marks

- 4. Explain the suspension systems for knee disarticulation.
- Describe the comparative biomechanics of quadrilateral & Ischial socket design of transfemoral prosthesis with neat sketch.
- Explain the measurement and casting procedure of transfemoral prosthesis.
- 7. Explain the Vaulting & Lateral trunk bending gait deviations.
- 8. Explain the rectification procedure of transfemoral quadrilateral socket.
- 9. Explain the biomechanics of knee disarticulation prosthesis with neat sketch.
- 10. What are the causes of amputation? Write the different level of lower limb amputation with neat sketch?
- 11. Write the care, maintenance & instructions to be given before discharging the prosthesis.

SHORT ANSWERS TYPE (Answer any Ten)

10 x 3 = 30 Marks

- 12. Write the location and function of Silesian belt.
- 13. Define medial & lateral whip.
- 14. Write the components of exoskeleton transfemoral prosthesis.
- 15. Write the reason for giving initial flexion of the socket in transfemoral prosthesis.
- Define single axis foot.
- Draw Scarpa's triangle with neat diagram.
- Write the advantage & disadvantages of brim casting.
- Write about the Voluntary and involuntary knee control.
- 20. Write the advantages of Total contact socket.
- 21. Define prosthesis and prosthetics.
- 22. What is Myodesis and Myoplasty?
- 23. Explain the self-suspension used for transfemoral prosthesis.

