

Printed Pages: 4

NIC - 501

(Following Paper ID and Roll No. to be filled in your Answer Books)

Paper ID : 2280454

Roll No.

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B. TECH.

Regular Theory Examination (Odd Sem-V) 2016-17

CONTROL SYSTEMS - I

Time : 3 Hours

Max. Marks : 100

Section - A

1. Attempt all parts. All parts carry equal marks. Write answer of each part in short. (10×2=20)
- a) Distinguish between open loop and closed loop control system.
 - b) Write the analogous electrical elements in force voltage analogy for the elements of mechanical translational system.
 - c) Derive the step response of a first order system.
 - d) Why negative feedback is invariably preferred in closed loop system?
 - e) What are the basic properties of signal flow graph?
 - f) What is a polar plot?
 - g) What do you understand by type and order of a system?
 - h) What is servomechanism?

501/12/2016/6700

(1)

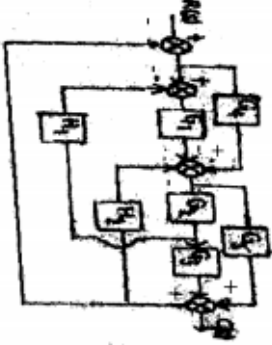
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- NIC - 501**
- i) State angle and magnitude criteria in root locus.
 - j) Define state, State Variable State Space Vector.

Section - B

2. Attempt any five parts from this section. (5×10=50)

- a) Determine the transfer function C(s)/R(s) for the block diagram shown in figure given below by using Block Diagram Reduction Method.



- b) Construct the state model for a system characterized by differential equation:-

$$\frac{d^3 y}{dt^3} = 6 \frac{d^2 y}{dt^2} + 11 \frac{dy}{dt} + 6y = u$$

- c) A unity feedback control system is characterized by an open-loop transfer function

$$G(s)H(s) = \frac{K}{s(s+10)}$$

501/12/2016/6700 (2)

NIC - 501

Determine the system gain K, so that the system will have a damping ratio of 0.5. For this value of K, find the rise time, peak time, settling time and peak overshoot.

- d) i) Explain the correlation between Transfer function and state space equations.
- ii) Derive the transfer function for Armature controlled DC Servo motor.

e) Obtain the time response of the following system:

$$\begin{bmatrix} \dot{X}_1 \\ \dot{X}_2 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} X_1 \\ X_2 \end{bmatrix} + \begin{bmatrix} 1 \\ 1 \end{bmatrix} u$$

where u(t) is a unit step occurring at t = 0 and $X^T(0) = [1 \ 0]$

- f) i) Draw the response of second order system for critically damped case and when input is unit step.
- ii) Derive the expressions for Rise time, Peak time, and peak overshoot.

g) The open loop transfer function of a system is $G(s)H(s) = \frac{k(s+1)}{(s^3+bs^2+3s+1)}$. Determine the values of 'k' & 'b' so that system will oscillate at frequency of 2rad/sec by using R-H criteria.

h) What is the role of sensors and encoders in control system? Explain the construction and principle of potentiometer.

501/12/2016/6700 (3)

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NIC - 501

Section - C

Note: Attempt any two questions from this section.

(2×15=30)

3. Sketch the root loci for the open loop transfer function given below (The gain K is assumed to be positive) and determine whether a system is stable or not:

$$G(s)H(s) = \frac{k}{s(s+1)(s^2+4s+13)}$$

4. Sketch the bode plot of the system given by:

$$G(s)H(s) = \frac{k}{s(s+0.5)(s^2+0.6s+10)}$$
 and determine the stability of the system.

5. State Nyquist stability criterion. Investigate the stability of a closed loop system with open loop transfer function given by:

$$G(s)H(s) = \frac{K(s+3)}{s(s-1)}$$

by using Nyquist plot. Also find the value of Gain margin.