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(10x1 = 10)

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	B TECH (SEM 7) THEORY EXAMINATION 2017-18 ELECTRIC DRIVES																															
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4.

Calculate initial and final equilibrium speeds.
b) Explain different type of braking of induction motor

Attempt any one parts of the following

a) Drive expression energy consumption $E = 0.5 \text{ Jw}_0^2$ on no load during starting of dc motor.

m initially the drive is operating in steady state. The characteristics of load torque are changed to T1 = -100, N-m.



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- b) A 220 V, 970 rpm, 100 A dc separately excited motor has an armature resistance of 0.05 ohms. It is broken by plugging from an initial speed of 1000 rpm. calculate
 - Value of resistance to be placed in armature circuit to limit braking current to twice the full load value.
 - b. braking torque
- Attempt any one parts of the following

(10x1 = 10)

- a) What are components of load torque and explain each .
- b) Draw the block diagram of an electric drive. Explain the function of each.
- 6. Attempt any one parts of the following

(10x1 = 10)

- a) What are the reasons for using load equalization in an electrical drives?
- b) A rolling mill driven by thyristors converter –fed dc motor operates on a speed reversing duty cycle. Motor field current is maintained constant at the rated value. Moment of inertia referred to the motor shaft is 10000 kg-m². Find torque during speed reversal from 200 to -200 rpm in 5 sec.
- Attempt any one parts of the following

(10x1 = 10)

- a) Derive the thermal model of motor for heating and cooling.
- b) A 220 volt , 200 A , 800 rpm dc separately excited motor has an armature resistance of $0.06~\Omega$. The motor armature is fed from a variable voltage source with an internal resistance of $0.04~\Omega$. calculate internal voltage of the variable voltage source when motor is operating in regenerative braking at 80% of rated motor torque and 600 rpm .

