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B.Tech IV Year I Semester (R07) Supplementary Examinations December 2015 MICROCONTROLLERS & APPLICATIONS

(Electronics & Communication Engineering)

(For 2008 regular admitted batch only)

Time: 3 hours

Max. Marks: 80

Answer any FIVE questions All questions carry equal marks

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- 1 (a) Determine whether the 8051 can be made to execute a single program instruction using external circuitry only without the help of software.
 - (b) Can we use 12 MHz Xtal for 8051 microcontroller to implement serial communication. What are the drawbacks and how to overcome them?
- 2 (a) What is a instruction and explain briefly about the instruction format of 8051 microcontroller?
 - (b) Write a program to shift a string of data of length n to another location such that there is an overlap of certain locations of source and destination.
- 3 (a) Explain interrupt latency, interrupt response time and interrupt recovery time in real time operating system.
 - (b) Discuss the interrupt structure of 8051. Mention the priority. Explain how least priority is made as highest priority.
- 4 (a) What are the limitations in pulse counting in micro controller? How to count the pulses appearing at a very high rate using microcontrollers?
 - (b) How do you set the registers TH & TL when changing the frequency of operation?
- 5 (a) Assume that a 2-digit BCD data is available in Reg A, as a packed BCD number. Write an assembler code to drive 7 segment display driver subroutine to display the two digits one after another on single 7 segment display.
 - (b) Draw an interface for 3 scan lines and 5 return lines in a keypad.
- 6 (a) What are the rules to be followed by the interrupt routines in RTOS?
 - (b) Explain round robin pre-emptive multi-tasking algorithm.
- 7 (a) Assume crystal frequency = 12 MHz implement a time delay loop for the generation of 50 ms delay using the instructions of 80196. Do not use timer of microcontroller.
 - (b) Explain about the interrupts of 80196 microcontrollers.
- 8 (a) Give the overview of the memory organization in ARM processors.
 - (b) Explain how a constant is loaded into a general purpose register of ARM processor.
 - (c) What is a thumb state? Explain.
