

Code: 9A05603

R09

B.Tech III Year II Semester (R09) Supplementary Examinations December/January 2015/2016

OPTIMIZING TECHNIQUES

(Common to CSE and CSS)

Time: 3 hours

Max Marks: 70

Answer any FIVE questions
All questions carry equal marks

- 1 Carry out a single-variable search to minimize the function:

$$f(x) = 3x^2 + \frac{12}{x^3} - 5 \quad \text{on the interval} \quad \frac{1}{2} \leq x \leq \frac{5}{2}$$

Using golden section method (use four functional evaluations only).

- 2 Minimize $f = 4x_1^2 + 3x_2^2 - 5x_1x_2 - 8x_2$ starting from the point (0, 0) using Powell's method. Perform two iterations.

- 3 Solve the following LP problem using Simplex method and comment on the result:

$$\begin{aligned} \text{Maximize } Z &= 3X_1 + 2X_2 \\ X_1 - X_2 &\leq 1 \\ X_1 + X_2 &\geq 3 \\ X_1, X_2 &\geq 0 \end{aligned}$$

- 4 Describe the transportation problem. Formulate the transportation problem as a linear programming problem.

- 5 (a) Define a convex programming. What is the Lagrangian function associated with it?
(b) Solve the following non-linear programming problem using Kuhn-Tucker conditions.

$$\begin{aligned} \text{Minimize } Z &= -\log x_1 - \log x_2 \\ \text{subject to the constraint} \\ x_1 + x_2 &\leq 2 \quad \text{and} \quad x_1, x_2 \geq 0 \end{aligned}$$

- 6 Solve the following problem using MOM technique:

$$\begin{aligned} \text{Minimize } f(x) &= (x_1 - 1)^2 + (x_2 - 1)^2 \\ \text{subject to } -x_1 &\leq 0 \\ -x_2 &\leq 0 \\ x_1^2 + x_2^2 - 1 &\leq 0 \end{aligned}$$

- 7 What is meant by quadratic programming? How does a quadratic programming problem differ from a linear programming problem? Give an example.

- 8 (a) What is a critical path? Why is it so important in scheduling and controlling large projects? Can a critical path change during the course of a project? Why?

- (b) A project has the following characteristics:

Activity	1-2	1-4	1-7	2-3	3-6	4-5	4-8	5-6	6-9	7-8	8-9
Duration	3	2	1	3	2	4	6	5	4	4	5

Construct a network and find critical path, total duration of the project.