

Code No: 07A7EC16

R07**Set No. 2**

IV B.Tech I Semester Examinations, November 2010
MICRO CONTROLLERS AND APPLICATIONS
Common to Bio-Medical Engineering, Electronics And Telematics,
Electronics And Communication Engineering

Time: 3 hours

Max Marks: 80

Answer any FIVE Questions
All Questions carry equal marks

1. (a) List non-maskable and maskable interrupts in 80196
(b) Draw an interrupt vector table according to hardware priority of each source group. [8+8]
2. (a) Give the programmer model of ARM.
(b) Explain SWI instruction in ARM and give its applications. [8+8]
3. Bring out the functional difference between microprocessors and microcontroller by drawing their basic block diagrams. [16]
4. (a) How do you choose scheduling strategy for the periodic, aperiodic and sporadic tasks?
(b) How does a preemptive event occur? [8+8]
5. (a) What are the SFR (special function registers) addresses.
(b) How you can access the SFR. [8+8]
6. (a) Give procedure to reset TMOD register.
(b) Does programming TMOD register effects PSW? If so how? [8+8]
7. (a) If a pneumatic actuator is to be driven by a microcontroller, what kind of interface is needed?
(b) What are the limitations in pulse counting in micro controller? How to count pulses appearing at a very high rate using microcontrollers? [8+8]
8. How do you access RAM, I/O, ports using bit addresses? [16]

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1. (a) What is the difference between “polling the busy line” and “software delay” in case of an LCD interfacing problem?
 (b) Explain the advantages of an optoisolator circuit. [8+8]
2. (a) What are the advantages of time slice scheduling by an RTOS?
 (b) Explain three ways in which an RTOS handles the ISRS in a multitasking environment [8+8]
3. Discuss different kinds of instructions and give two examples for each. [16]
4. (a) What is meant by Thumb state and ARM state? What are the advantages and disadvantages of using Thumb state?
 (b) Explain how ARM -Thumb Interworking takes place. [10+6]
5. Find the timer’s clock frequency and its period for any two 8051 based systems, with a crystal frequency of 8MHz. [16]
6. Discuss the hardware requirements to needed to implement vectored or polled interrupts. [16]
7. Give flag settings of the following instructions. [8×2]
 - (a) ADDC
 - (b) RRC
 - (c) SETBC
 - (d) POP
 - (e) XCH
 - (f) CLR
 - (g) ORL
 - (h) ANL.
8. (a) Explain the software times interrupt in 80196
 (b) Justify the priority orders provided in 80196 for the maskable interrupts
 (c) What are vector addresses for Interrupt servicing to timer 1 and timer 2 in Intel 80196? [5+5+6]

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R07**Set No. 1**

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1. Write a program to find the number of ones in register R2. [16]
2. (a) Write the help of a block diagram explain the parallel port interface for the printer, also use RS-232 serial interface and explain.
 (b) Write brief note on IEEE 488 GPIB signals. [8+8]
3. (a) Explain the basic architecture of the kernel. What are the kernel objects?
 (b) With the help of state diagram explain different task states [8+8]
4. (a) How do we program bit rate/clock rate during the synchronous function in an 80196? Explain for a bit rate of 9600 bud/sec
 (b) What is an overrun error?
 (c) For a 12 MHZ crystal with 80196, what is the period between the two inputs to FRC timer 1? [16]
5. (a) Explain the stack operations in ARM.
 (b) What happens if a software interrupt instruction SWI is executed?
 (c) Explain BIC instruction of ARM. [5+6+5]
6. How does a serial data buffer can communicates data serially. [16]
7. What is counter programming in 8051 microcontroller? [16]
8. Write a program to test the RAM of 8051 μ C and explain. [16]

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R07**Set No. 3**

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1. (a) Why do we have to isolate an MCU sort I/O pins from a physical system?
 (b) Explain the circuit used to interface to an optoisolator.
 (c) Write a brief note on linear incremental encoder in a shaft. [5+5+6]
2. Discuss briefly how a CPU can resolve priorities by giving a specific algorithm and explain in detail. [16]
3. Write short notes on the following:
 - (a) Data transfer instructions.
 - (b) Bit manipulation instructions.
 - (c) Internal RAM. [5+5+6]
4. (a) List the best strategies for synchronisation between the tasks and ISRS.
 (b) Explain the terms process descriptor and process control block [16]
5. (a) Explain the pipeline executing characteristics of ARM? Take an example ARM instruction sequence and explain?
 (b) Explain the difference between Exception handling & Interrupt handling in ARM. [10+6]
6. What are the methodologies adopted in organizing register banks 0 to 3. [16]
7. (a) We need to find the total number of transactions at the input of 80196. How do we program HSI-MODE Register?
 (b) Justify the priority orders provided in 80196 for the non-maskable interrupts? [8+8]
8. Design a speed control system for a two wheeler using timers. [16]
