II B.Tech I Semester Examinations,November 2010 ELECTRICAL ENGINEERING
Common to Mechanical Engineering, Chemical Engineering, Mechatronics, Production Engineering

## Answer any FIVE Questions <br> All Questions carry equal marks

1. (a) Explain with a neat sketch,the principle of operation of a D.C.motor.
(b) A 4-pole series motor has 944 wave connected armature conductors. At a certain load the flux per pole is 34.6 mwb and the total mechanical torque developed is $209 \mathrm{~N}-\mathrm{m}$. Calculate the line current taken by the motor and the speed at which it will run with an applied voltage of 500 V . Given $\mathrm{R}_{\mathrm{a}}=3 \Omega$.

$$
[8+8]
$$

2. (a) Determine the condition for maximum efficiency of a D.C generator.
(b) A d. c. generator generates an e.m.f. of 520 V . If has 2,000 armature conductors, flux per pole of 0.013 wb , speed of 1200 r.p.m and the armature winding has four parallel paths. Find the number of poles.
(c) Calculate the flux in a 4 -pole dynamo with 722 armature conductors generating 500 V when running at 1000 r.p.m, when the armature is
i. lap connected
ii. wave connected.
$[4+4+8]$
3. (a) Describe with neat sketches the constructional details of a salient pole type Alternator
(b) Find the no-load phase and line voltage of a star-connected 3-phase, 6-pole alternator which runs at 1200 rpm , having flux per pole of 0.1 Wb sinusoidally distributed. Its stator has 54 slots having double layer winding. Each coil has 8 turns and the coil is chorded by one slot.
4. (a) Define the following:
i. Absolute instruments
ii. Secondary instruments.
(b) A PMMC instrument with an internal resistance of $730 \Omega$ has a full scale current of 5 mA . It is to be converted into a multi range ammeter for ranges $1 \mathrm{~A}, 5 \mathrm{~A}, 25 \mathrm{~A}$ and 125 A using individual shunts for each range .Calculate the value of the individual shunts. $[4+12]$
5. (a) Explain why the rotor of poly phase induction motor can never attain synchronous speed.
(b) A 3- $\Phi$, 4-pole, 50 Hz induction motor has a full-load speed of 1440 rpm . Calculate the following:
i. full-load slip and rotor frequency
ii. speed of stator field with respect to
A. stator structure
B. rotor structure
iii. speed of rotor field with respect to
A. stator structure
B. rotor structure.
6. (a) Define self and mutual inductances. Establish the polarity of two mutually coupled coils on a single magnetic core.
(b) Find the voltage needed across terminals a-b shown in the figure 6 b so that the drop across the $10 \Omega$ resistor is 30 V . Also find the corresponding voltage drop across the $5 \Omega$ resistor.


Figure 6b
7. (a) Derive the emf equation of a $1-\Phi$ transformer and draw the no-load phasor diagram
(b) A 1- $\Phi$ transformer has 360 turns on the primary and 180 turns on the secondary. The respective resistance are $0.233 \Omega$ aND $0.067 \Omega$. Calculate the equivalent resistance of
i. the primary in terms of secondary windings
ii. the secondary in terms of primary windings
iii. the total resistance of the transformer in terms of primary.
8. (a) Define RMS value and Average Value of an alternating current..
(b) For the circuit shown (figure8b), determine the true power, reactive power and apparent power in each branch. What is the power factor of the total circuit?


Figure 8b


II B.Tech I Semester Examinations,November 2010 ELECTRICAL ENGINEERING
Common to Mechanical Engineering, Chemical Engineering, Mechatronics, Production Engineering Time: 3 hours

Max Marks: 80

Answer any FIVE Questions
All Questions carry equal marks

1. (a) Define self and mutual inductances. Establish the polarity of two mutually coupled coils on a single magnetic core.
(b) Find the voltage needed across terminals a-b shown in the figure 10 so that the drop across the $10 \Omega$ resistor is 30 V . Also find the corresponding voltage drop across the $5 \Omega$ resistor. $\quad[8+8]$


Figure 1b
2. (a) Explain why the rotor of poly phase induction motor can never attain synchronous speed.
(b) A 3- $\Phi$, 4-pole, 50 Hz induction motor has a full-load speed of 1440 rpm . Calculate the following:
i. full-load slip and rotor frequency
ii. speed of stator field with respect to
A. stator structure
B. rotor structure
iii. speed of rotor field with respect to
A. stator structure
B. rotor structure.
3. (a) Determine the condition for maximum efficiency of a D.C generator.
(b) A d. c. generator generates an e.m.f. of 520 V . If has 2,000 armature conductors, flux per pole of 0.013 wb , speed of 1200 r.p.m and the armature winding has four parallel paths. Find the number of poles.
(c) Calculate the flux in a 4-pole dynamo with 722 armature conductors generating 500 V when running at 1000 r.p.m, when the armature is
i. lap connected
ii. wave connected.

$$
[4+4+8]
$$

4. (a) Explain with a neat sketch,the principle of operation of a D.C.motor.
(b) A 4-pole series motor has 944 wave connected armature conductors. At a certain load the flux per pole is 34.6 mwb and the total mechanical torque developed is $209 \mathrm{~N}-\mathrm{m}$. Calculate the line current taken by the motor and the speed at which it will run with an applied voltage of 500 V . Given $\mathrm{R}_{\mathrm{a}}=3 \Omega$.

$$
[8+8]
$$

5. (a) Derive the emf equation of a $1-\Phi$ transformer and draw the no-load phasor diagram
(b) A $1-\Phi$ transformer has 360 turns on the primary and 180 turns on the secondary. The respective resistance are $0.233 \Omega$ aND $0.067 \Omega$. Calculate the equivalent resistance of
i. the primary in terms of secondary windings
ii. the secondary in terms of primary windings
iii. the total resistance of the transformer in terms of primary.
6. (a) Define RMS value and Average Value of an alternating current..
(b) For the circuit shown (figure6b), determme the true power, reactive power and apparent power in each branch. What is the power factor of the total circuit?


Figure 6b
7. (a) Define the following:
i. Absolute instruments
ii. Secondary instruments.
(b) A PMMC instrument with an internal resistance of $730 \Omega$ has a full scale current of 5 mA . It is to be converted into a multi range ammeter for ranges $1 \mathrm{~A}, 5 \mathrm{~A}, 25 \mathrm{~A}$ and 125 A using individual shunts for each range .Calculate the value of the individual shunts.
$[4+12]$
8. (a) Describe with neat sketches the constructional details of a salient pole type Alternator
(b) Find the no-load phase and line voltage of a star-connected 3 -phase, 6 -pole alternator which runs at 1200 rpm , having flux per pole of 0.1 Wb sinusoidally distributed. Its stator has 54 slots having double layer winding. Each coil has 8 turns and the coil is chorded by one slot.


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Time: 3 hours
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Answer any FIVE Questions
All Questions carry equal marks

1. (a) Define the following:
i. Absolute instruments
ii. Secondary instruments.
(b) A PMMC instrument with an internal resistance of 7305 has a full scale current of 5 mA . It is to be converted into a multi range ammeter for ranges $1 \mathrm{~A}, 5 \mathrm{~A}, 25 \mathrm{~A}$ and 125 A using individual shunts for each range .Calculate the value of the individual shunts.

$$
[4+12]
$$

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(b) A 4-pole series motor has 944 waye connected armature conductors. At a certain load the flux per pole is 34.6 mwb and the total mechanical torque developed is $209 \mathrm{~N}-\mathrm{m}$. Calculate the line current taken by the motor and the speed at which it will run with an applied voltage of 500 V . Given $\mathrm{R}_{\mathrm{a}}=3 \Omega$.

$$
[8+8]
$$

3. (a) Define RMS value and Average Value of an alternating current..
(b) For the circuit shown (figure3b), determine the true power, reactive power and apparent power in each branch. What is the power factor of the total circuit?


Figure 3b
4. (a) Derive the emf equation of a $1-\Phi$ transformer and draw the no-load phasor diagram
(b) A $1-\Phi$ transformer has 360 turns on the primary and 180 turns on the secondary. The respective resistance are $0.233 \Omega$ aND $0.067 \Omega$. Calculate the equivalent resistance of
i. the primary in terms of secondary windings
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5. (a) Determine the condition for maximum efficiency of a D.C generator.
(b) A d. c. generator generates an e.m.f. of 520 V . If has 2,000 armature conductors, flux per pole of 0.013 wb , speed of 1200 r.p.m and the armature winding has four parallel paths. Find the number of poles.
(c) Calculate the flux in a 4-pole dynamo with 722 armature conductors generating 500 V when running at 1000 r.p.m, when the armature is
i. lap connected
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6. (a) Explain why the rotor of poly phase induction motor can never attain synchronous speed.
(b) A 3- $\Phi$, 4-pole, 50 Hz induction motor has a full-load speed of 1440 rpm . Calculate the following:
i. full-load slip and rotor frequency
ii. speed of stator field with respect to
A. stator structure
B. rotor structure
iii. speed of rotor field with respect to
A. stator structure
B. rotor structure.

$$
[6+10]
$$

7. (a) Define self and mutual inductances. Establish the polarity of two mutually coupled coils on a single magnetic core.
(b) Find the voltage needed across terminals a-b shown in the figure 7 b so that the drop across the $10 \Omega$ resistor is 30 V . Also find the corresponding voltage drop across the $5 \Omega$ resistor.
[8+8]


Figure 7b
8. (a) Describe with neat sketches the constructional details of a salient pole type Alternator
(b) Find the no-load phase and line voltage of a star-connected 3-phase, 6-pole alternator which runs at 1200 rpm , having flux per pole of 0.1 Wb sinusoidally distributed. Its stator has 54 slots having double layer winding. Each coil has 8 turns and the coil is chorded by one slot.


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Time: 3 hours
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i. the primary in terms of secondary windings
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2. (a) Define self and mutual induetances. Establish the polarity of two mutually coupled coils on a single magnetic core.
(b) Find the voltage needed across terminals $a-b$ shown in the figure 2 b so that the drop across the $10 \Omega$ resistor is 30 V . Also find the corresponding voltage drop across the $5 \Omega$ resistor.


Figure 2b
3. (a) Explain why the rotor of poly phase induction motor can never attain synchronous speed.
(b) A 3- $\Phi$, 4 -pole, 50 Hz induction motor has a full-load speed of 1440 rpm . Calculate the following:
i. full-load slip and rotor frequency
ii. speed of stator field with respect to
A. stator structure
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A. stator structure
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(b) For the circuit shown (figure4b), determine the true power, reactive power and apparent power in each branch. What is the power factor of the total circuit?
[4+12]

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(c) Calculate the flux in a 4-pole dynamo with 722 armature conductors generating 500 V when running at $1000 \mathrm{r} . \mathrm{p} . \mathrm{m}$, when the armature is
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ii. wave connected.

$$
[4+4+8]
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