$\mathbf{R05}$

Set No. 2

II B.Tech II Semester Examinations,December 2010 SIGNALS AND SYSTEMS Common to Instrumentation And Control Engineering, Electronics And Computer Engineering

Time: 3 hours

Code No: R05221902

Max Marks: 80

Answer any FIVE Questions All Questions carry equal marks

- 1. (a) Find Z transform of the following:
 - i. n(n-1)u(n)
 - ii. n^2 u(n)
 - (b) Find inverse z transform of the following:

i.
$$\frac{1}{\left[1-\frac{1}{2}z^{-1}\right]^2}$$

ii. $3+2 \ z^{-1} + 6z^{-4}$

- 2. The signal $V(t) = \cos 5\Pi t + 0.5 \cos 10 \Pi t$ is instantaneously sampled. The interval between samples is T_S .
 - (a) Find the maximum allowable value for T_S .
 - (b) To reconstruct the signal $V_s(t)$ is passed through a rectangular low pass filter. Find the minimum filter bandwidth to reconstruct the signal without distortion.
 - (c) Explain signal recovery through holding. [4+6+6]
- 3. (a) Derive polar Fourier series from the exponential Fourier series representation and hence prove that $D_n = 2 |C_n|$
 - (b) Show that the magnitude spectrum of every periodic function is Symmetrical about the vertical axis passing through the origin. [8+8]
- 4. (a) Show that whether $\mathbf{x}(t) = \mathbf{A} e^{-\alpha(t)} \mathbf{u}(t), \alpha > 0$ is an energy signal or not.
 - (b) Prove that the complex exponential functions are orthogonal functions. [8+8]
- 5. (a) Compute the convolution of the following pair of signals x(t) and h(t) by calculating $X(\omega)$ and $H(\omega)$ using the convolution property and inverse transforming $x(t) = e^{-t}u(t), h(t) = e^{t}u(-t).$
 - (b) Suppose that $x(t) = e^{-(t-2)}u(t-2)$ and h(t) is as depicted in figure 4b. Verify the convolution property for this pair of signals by showing that the Fourier transform of y(t) = x(t) * h(t) equals $X(\omega)H(\omega)$. [8+8]



Figure 4b

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$\mathbf{R05}$

Set No. 2

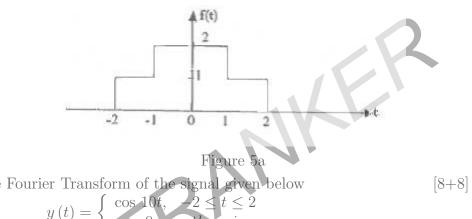
6. (a) State the properties of the ROC of L.T.

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(b) Determine the function of time x(t) for each of the following laplace transforms and their associated regions of convergence. [8+8]

i.	$\frac{(s+1)^2}{s^2-s+1}$	$\operatorname{Re}\{S\} > \frac{1}{2}$
ii.	$\frac{s^2 - s + 1}{\left(s + 1\right)^2}$	$\operatorname{Re}\left\{S\right\} > -1$

7. (a) Find the Fourier Transform of the waveform shown figure 5a.



(b) Find the Fourier Transform of the signal given below $y(t) = \begin{cases} \cos 10t, & -2 \le t \le 2\\ 0, & otherwise \end{cases}$

- (a) Explain the difference between the following systems. 8.
 - i. Linear and non-linear systems.
 - ii. Time variant and time invariant systems.
 - (b) Consider a causal LTI system with frequency response $H(jw) = \frac{1}{3+jw}$. For a particular input x(t) this system is observed to produce the output y(t) = $e^{-3t}u(t) - e^{-4t}u(t)$. Find x(t). [8+8]

 $\mathbf{R05}$

Set No. 4

II B.Tech II Semester Examinations,December 2010 SIGNALS AND SYSTEMS Common to Instrumentation And Control Engineering, Electronics And Computer Engineering

Time: 3 hours

Code No: R05221902

Max Marks: 80

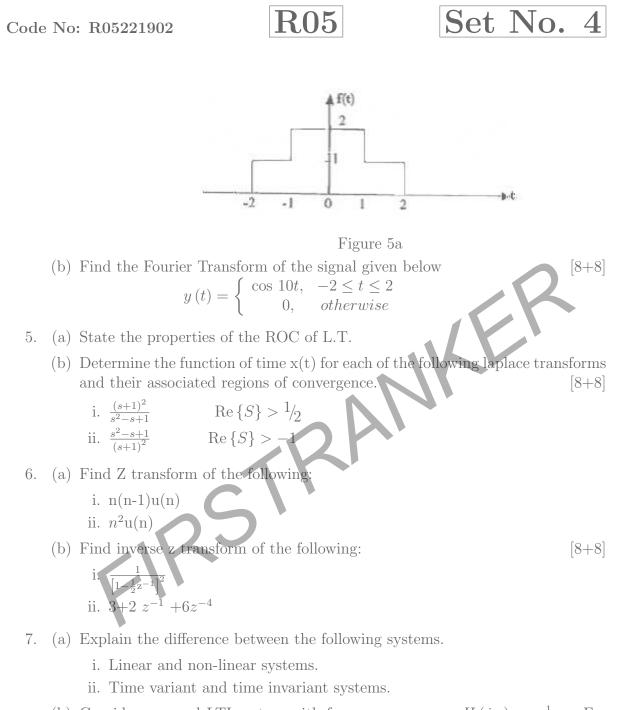
Answer any FIVE Questions All Questions carry equal marks

- ****
- 1. The signal $V(t) = \cos 5\Pi t + 0.5 \cos 10 \Pi t$ is instantaneously sampled. The interval between samples is T_S .
 - (a) Find the maximum allowable value for T_S .
 - (b) To reconstruct the signal $V_s(t)$ is passed through a rectangular low pass filter. Find the minimum filter bandwidth to reconstruct the signal without distortion.
 - (c) Explain signal recovery through holding. [4+6+6]
- 2. (a) Derive polar Fourier series from the exponential Fourier series representation and hence prove that $D_n = 2|C_n|$
 - (b) Show that the magnitude spectrum of every periodic function is Symmetrical about the vertical axis passing through the origin. [8+8]
- 3. (a) Compute the convolution of the following pair of signals $\mathbf{x}(t)$ and $\mathbf{h}(t)$ by calculating $\mathbf{X}(\omega)$ and $\mathbf{H}(\omega)$ using the convolution property and inverse transforming $x(t) = e^{-t}u(t), \ h(t) = e^tu(-t).$
 - (b) Suppose that $x(t) = e^{-(t-2)}u(t-2)$ and h(t) is as depicted in figure 4b. Verify the convolution property for this pair of signals by showing that the Fourier transform of y(t) = x(t) * h(t) equals $X(\omega)H(\omega)$. [8+8]



Figure 4b

4. (a) Find the Fourier Transform of the waveform shown figure 5a.

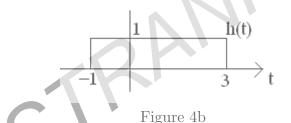


- (b) Consider a causal LTI system with frequency response $H(jw) = \frac{1}{3+jw}$. For a particular input x(t) this system is observed to produce the output $y(t) = e^{-3t}u(t) - e^{-4t}u(t)$. Find x(t). [8+8]
- 8. (a) Show that whether $x(t) = A e^{-\alpha(t)} u(t)$, $\alpha > 0$ is an energy signal or not.
 - (b) Prove that the complex exponential functions are orthogonal functions. [8+8]

Set No. 1 $\mathbf{R05}$ Code No: R05221902 **II B.Tech II Semester Examinations, December 2010** SIGNALS AND SYSTEMS Common to Instrumentation And Control Engineering, Electronics And **Computer Engineering** Time: 3 hours Max Marks: 80

Answer any FIVE Questions All Questions carry equal marks

- 1. (a) Compute the convolution of the following pair of signals x(t) and h(t) by calculating $X(\omega)$ and $H(\omega)$ using the convolution property and inverse transforming $x(t) = e^{-t}u(t), h(t) = e^{t}u(-t).$
 - (b) Suppose that $x(t) = e^{-(t-2)}u(t-2)$ and h(t) is as depicted in figure 4b. Verify the convolution property for this pair of signals by showing that the Fourier transform of y(t) = x(t) * h(t) equals $X(\omega)H(\omega)$. [8+8]



2. (a) Explain the difference between the following systems.

i. Linear and non-linear systems.

ii. Time variant and time invariant systems.

- (b) Consider a causal LTI system with frequency response $H(jw) = \frac{1}{3+jw}$. For a particular input x(t) this system is observed to produce the output $y(t) = e^{-3t}u(t) - e^{-4t}u(t)$. Find x(t). [8+8]
- 3. (a) Show that whether $x(t) = A e^{-\alpha(t)} u(t)$, $\alpha > 0$ is an energy signal or not.
 - (b) Prove that the complex exponential functions are orthogonal functions. [8+8]
- 4. (a) State the properties of the ROC of L.T.
 - (b) Determine the function of time x(t) for each of the following laplace transforms and their associated regions of convergence. [8+8]

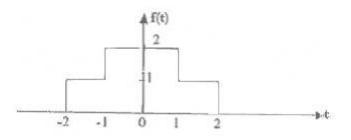
i.
$$\frac{(s+1)^2}{s^2-s+1}$$
 Re $\{S\} > \frac{1}{2}$
ii. $\frac{s^2-s+1}{(s+1)^2}$ Re $\{S\} > -1$

5. (a) Find the Fourier Transform of the waveform shown figure 5a.

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- (b) Find the Fourier Transform of the signal given below $y(t) = \begin{cases} \cos 10t, & -2 \le t \le 2\\ 0, & otherwise \end{cases}$
- 6. (a) Derive polar Fourier series from the exponential Fourier series representation and hence prove that $D_n = 2 |C_n|$
 - (b) Show that the magnitude spectrum of every periodic function is Symmetrical about the vertical axis passing through the origin. [8+8]
- 7. The signal $V(t) = \cos 5\Pi t + 0.5 \cos 10\Pi t$ is instantaneously sampled. The interval between samples is T_S .
 - (a) Find the maximum allowable value for T_S .
 - (b) To reconstruct the signal $V_s(t)$ is passed through a rectangular low pass filter. Find the minimum filter bandwidth to reconstruct the signal without distortion.
 - (c) Explain signal recovery through holding. [4+6+6]
- 8. (a) Find Z transform of the following:
 - i. n(n-1)u(n)
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 - (b) Find inverse z transform of the following:

[8+8]

[8+8]

i. $\frac{1}{\left[1-\frac{1}{2}z^{-1}\right]^2}$ ii. $3+2 \ z^{-1} + 6z^{-4}$

 $\mathbf{R05}$



II B.Tech II Semester Examinations,December 2010 SIGNALS AND SYSTEMS Common to Instrumentation And Control Engineering, Electronics And Computer Engineering

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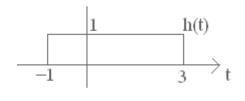
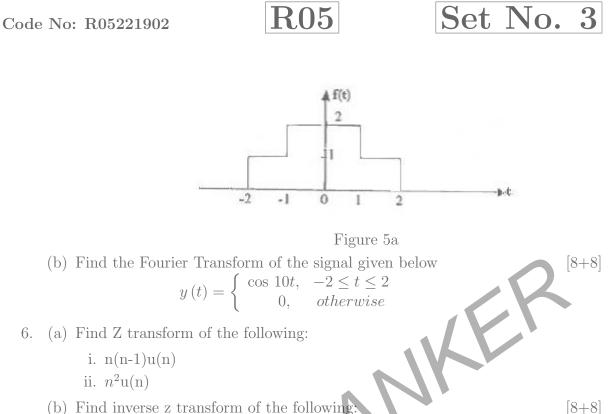


Figure 4b

5. (a) Find the Fourier Transform of the waveform shown figure 5a.



- (b) Find inverse z transform of the following
 - i. $\frac{1}{\left[1 \frac{1}{2}z^{-1}\right]^2}$ ii. $3+2 z^{-1} + 6z^{-4}$
- (a) Derive polar Fourier series from the exponential Fourier series representation 7. and hence prove that $D_n = 2|C_n|$
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