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Code No: **R41028**

R10

IV B.Tech I Semester Supplementary Examinations, October/November - 2017

OPTIMIZATION TECHNIQUES

(Mechanical Engineering)

Time: 3 hours

Max. Marks: 75

Answer any FIVE Questions All Questions carry equal marks

***** 1 Write the typical applications of optimization in the field of electrical engineering. [7] a) What are the differences between a constraint surface and a composite constraint b) surface? [8] State the Kuhn–Tucker conditions. 2 a) [7] b) Find the dimensions of a cylindrical tin (with top and bottom) made up of sheet metal to maximize its volume such that the total surface area is equal to $A_0 = 24 \pi$. [8] 3 a) Define the following terms: point, hyperplane, convex set, extreme point. [7] b) Maximize $f = 240x_1 + 104x_2 + 60x_3 + 19x_4$ Subject to $20x_1 + 9x_2 + 6x_3 + x_4 \le 20$ $10x_1 + 4x_2 + 2x_3 + x_4 \le 10$ $x_i \ge 0, i = 1 \text{ to } 4$ Find all the basic feasible solutions of the problem and identify the optimal solution. [8] 4 How do you overcome (i) Redundancy and (ii) Degeneration in transportation problems. [15] What are the differences between elimination and interpolation methods? 5 [7] a) Find the value of x in the interval (0, 1) which minimizes the function f = x(x - x)b) 1.5) to within ± 0.05 by the Fibonacci method. [8] What are the roles of univariate and pattern moves in the Powell's method? 6 a) [7] Perform two iterations of the steepest descent method to minimize the function of b) $(x_1, x_2) = 100(x_2 - x_1^2)^2 + (1 - x_1)^2$ from the starting point (-1.2, 1.0)^T. [8] Why is handling of equality constraints difficult in the penalty function methods? 7 a) [7] Minimize f $(x_1, x_2) = 13 (x_1 + 1)^3 + x_2$ b) Subject to $g_1(x_1, x_2) = -x_1 + 1 \le 0$ $g_2(x_1, x_2) = -x_2 \le 0$ [8] 8 a) Explain the computational procedure used in dynamic programming. [7] State Bellman's principle of optimality and explain by an illustrative example how b) it can be used to solve multistage decision problem. [8]