Roll No. of Pages: 02

Total No. of Questions: 09

B.Tech.(CSE) (2011 Onwards) (Sem.-5) COMPUTER GRAPHICS

Subject Code: BTCS-504
Paper ID: [A2100]

Time: 3 Hrs.

Max. Marks: 60

INSTRUCTION TO CANDIDATES:

- SECTION-A is COMPULSORY consisting of TEN questions carrying TWO marks each.
- 2. SECTION-B contains FIVE questions carrying FIVE marks each and students have to attempt any FOUR questions.
- 3. SECTION-C contains THREE questions carrying TEN marks each and students have to attempt any TWO questions.

SECTION A

1. Write briefly:

- a. What is difference between raster scan systems and random scan systems?
- b. What do you mean by persistence?
- c. Why computer generated lines which are not parallel to x-axis or y-axis and which are not inclined at $\pm 45^{\circ}$ to x-or y-axis appears to be zigzagged?
- d. What is the relationship between the rotations R_{Θ} , R_{Θ} and R_{Θ}^{--} ?
- e. Define window and viewport.
- f. What is meant by coherence? List various types of coherence techniques.
- g. Differentiate between parallel and perspective projections.
- h. What are principal vanishing points?
- i. What do you mean by anti-aliasing?
- i. What are fractals?

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SECTION-B

- 2. Find the form of transformation matrix for reflection about a line L with slope m and y-intercept (0, b).
- 3. Describe in detail Nicholl-Lee-Nicholl line clipping algorithm.
- 4. Describe in detail z-buffer algorithm for visible surface detection.
- 5. What are seed-fill algorithms? Write 8-connected region filling algorithm? Out of 4-connected and 8-connected seed fill algorithm, which algorithm would you use to fill 8-connected boundary region?
- 6. Find out the conditions under which scaling and rotation forms a commutative pair of operations.

SECTION-C

- 7. a. Explain in detail Midpoint algorithm for scan converting a circle.
 - b. Using Midpoint circle generation algorithm, compute the coordinates of points that lie on the circumference of the circle with radius 5 and center as (7,7).
- 8. a. Derive the general perspective transformation onto a plane with reference point $R_0(x_0,y_0,z_0)$, normal vector $N=n_1I+n_2J+n_3K$, using C(a,b,c) as the centre of projection.
 - b. What are homogeneous coordinates? What role do they play in composite transformations?
- 9. a. Explain Gourard method for shading.
 - b. Write short note on ray-tracing.

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