

# GUJARAT TECHNOLOGICAL UNIVERSITY

BE - SEMESTER-VIII (NEW) - EXAMINATION – SUMMER 2018

Subject Code: 2180208

Date: 30/04/2018

Subject Name: Computer Integrated Manufacturing in Automobile Industry (Department Elective II)

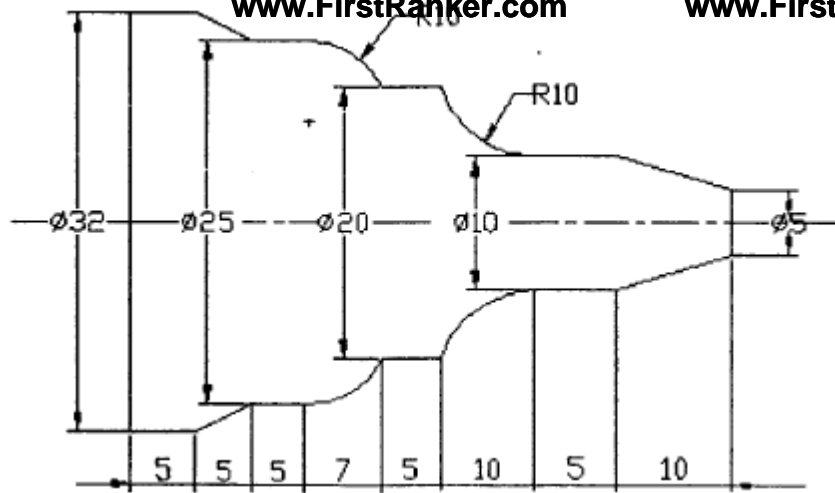
Time: 10:30 AM to 01:00 PM

Total Marks: 70

Instructions:

1. Attempt all questions.
2. Make suitable assumptions wherever necessary.
3. Figures to the right indicate full marks.

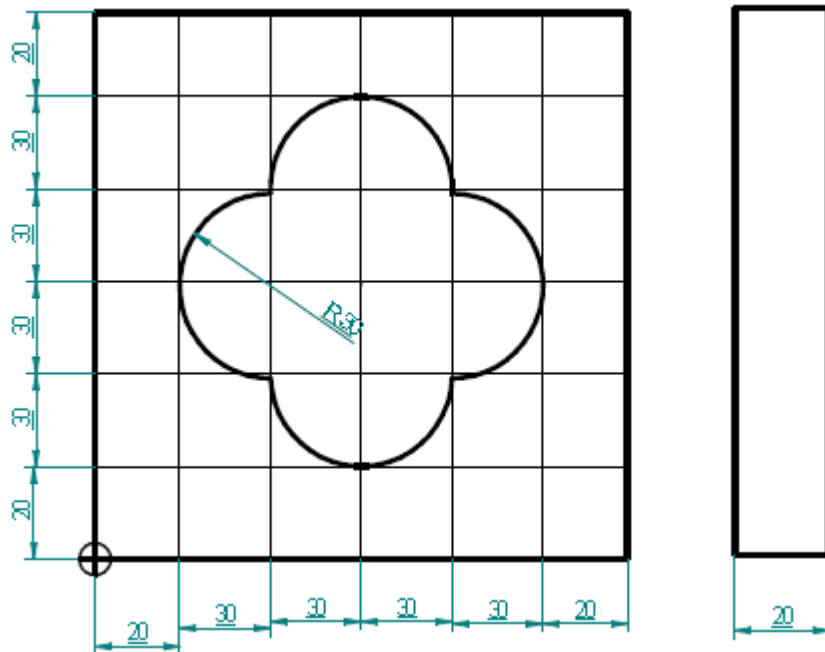
		MARKS
<b>Q.1</b>	(a) State Objectives and scope of Computer Integrated Manufacturing.	<b>03</b>
	(b) Classify the CNC machine on the basis of :	<b>04</b>
	i) Programming method	
	ii) Type of Feedback System	
	(c) What are the basic components of numeric control system? Draw and discuss the function of each components.	<b>07</b>
<b>Q.2</b>	(a) What is tool compensation? Explain tool length and cutter radius compensation.	<b>03</b>
	(b) Explain OPTIZ classification and coding system.	<b>04</b>
	(c) What is PLC? Explain major components of PLC.	<b>07</b>
	List Application of PLC.	
	<b>OR</b>	
	(c) What is Group Technology? Explain the Concept of part family.	<b>07</b>
<b>Q.3</b>	(a) Define Robot. Enlist different elements of robot.	<b>03</b>
	(b) Give difference between MRP-I and MRP-II.	<b>04</b>
	(c) Explain Tool Supply system in FMS.	<b>07</b>
	<b>OR</b>	
<b>Q.3</b>	(a) Discuss various applications of robots.	<b>03</b>
	(b) Explain JIT technique in brief.	<b>04</b>
	(c) What are the different types of grippers used in robot? Explain any two in detail.	<b>07</b>
<b>Q.4</b>	(a) Distinguish between variant and generative type CAPP.	<b>03</b>
	(b) List different flexibilities associated with FMS. Explain any two in brief.	<b>04</b>
	(c) Discuss concept of Computer Vision & Machine Intelligence.	<b>07</b>
	<b>OR</b>	
<b>Q.4</b>	(a) Write a general syntax of G81 canned cycle.	<b>03</b>
	(b) Describe Automated Assembly Line.	<b>04</b>
	(c) Discuss Automated Guided Vehicles and cellular manufacturing.	<b>07</b>
<b>Q.5</b>	(a) What is quantitative analysis of assemble line?	<b>03</b>
	(b) Name the relative merits and demerits of different types of robot configuration.	<b>04</b>
	(c) Write a manual part Programme using appropriate G & M codes to turn a given below profile.	<b>07</b>



All Dimensions are in mm. Assume suitable data if necessary.

OR

- Q.5**
- |     |   |           |
|-----|---|-----------|
| (a) | State main problems associated with manual process planning.  | <b>03</b> |
| (b) | Describe concept of transfer line.  | <b>04</b> |
| (c) | Prepare a Part Programme with appropriate G/M codes to mill the component as per given below drawing. | <b>07</b> |



All Dimensions are in mm. Assume suitable data if necessary.

\*\*\*\*\*