

Code No: R32043 m R10

Set No. 1

III B.Tech II Semester Supplementary Examinations, April - 2017 DIGITAL SIGNAL PROCESSING

(Common to, Electronics and Communications Engineering, Electronics and Computer Engineering)

Time: 3 hours Max. Marks: 75

Answer any FIVE Questions All Questions carry equal marks

- 1 a) For each of the following impulse responses given below, determine if the corresponding system is causal and stable with appropriate reasons [7M]
 - i) $h(n) = \sin\left(\frac{n\pi}{2}\right)$ ii) $h(n) = \rho^{2n}u(n-1)$
 - b) Determine the impulse response of the following causal systems i) y(n)-y(n-1)=x(n)+x(n-1)
 - ii) $y(n) \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2) = x(n)$
- 2 a) Find the Z transforms of $x(n) = \left(\frac{1}{4}\right)^n u(n) + \left(\frac{1}{5}\right)^n u(-n-1)$ b) Let x[n] be a discrete periodic $x(n) = \left(\frac{1}{4}\right)^n u(n) + \left(\frac{1}{5}\right)^n u(-n-1)$
 - b) Let x[n] be a discrete periodic signal with period N whose Fourier series coefficients are k a with period N. Determine the Fourier series coefficients of the signal y(n)=x(n)-x(n-1)
- 3 a) Find the 8 point DFT of the following sequence using Decimation In Time(DIT) [7M] FFT algorithm $x(n)=\cos(2\pi n)$
 - b) Find the 10-point inverse DFT of $X(k) = \begin{cases} 3 & k=0 \\ 2 & k=3,7 \\ 1 & else \end{cases}$ [8M]
- 4 a) Realize the following filter function using the direct form-I and II realizations $y(n) \frac{2}{5}y(n-1) + \frac{3}{7}y(n-2) = 2x(n) + \frac{2}{3}x(n-1)$ [7M]
 - b) Explain about lattice structure with appropriate equations and diagrams. Determine the FIR filter coefficients for the direct form structure having three stage latter filter coefficients given by $K_1 = \frac{1}{4}$, $K_2 = \frac{1}{4}$, $K_3 = \frac{1}{3}$

1 of 2



Code No: **R32043 R10**

Set No. 1

- Convert the following analog filter with system equation $H(s) = \frac{s + 0.1}{(s + 0.1)^2 + 9}$ into a digital IIR filter using impulse invariance method. The resultant digital filter should have a resonant frequency of $\omega_i = \frac{\pi}{4}$
 - b) Using bilinear transformation, design a digital Butterworth filter with the following specifications i) sampling frequency $F_s = 8 \text{KHz}$, ii) $\alpha_p = 2dB$ in the passband $800 \, Hz \le f \le 1000 \, Hz$ iii) $\alpha_s = 20 \, dB$ in the stopband $0 \le f \le 400 \, Hz$ and $2000 \, Hz \le f \le \infty$
- 6 a) Design a linear phase highpass filter using the Hamming window for the following desired frequency response [8M]

$$H_{d}(w) = \begin{cases} e^{-j3\omega} & \text{for } \frac{\pi}{6} \leq |\omega| \leq \pi \\ 0 & |\omega| < \frac{\pi}{6} \end{cases} \quad \text{and} \quad \omega(n) = 0.54 - 0.46 \cos\left(\frac{2\pi n}{N-1}\right)$$

where N is the length of the Hamming window.

- b) What is a Kaiser window? Explain the design of a FIR filter using Kaiser window. [7M]
- 7 a) What is multirate signal processing? Explain different applications of multirate [8M] signal processing.
 - b) Design a 24kHz to 16kHz sample rate converter and show how this converter can be [7M] efficiently realised.
- 8 a) Compare a general purpose processor and digital signal processor. [8M]
 - b) Explain the key features of a digital signal processor with neat diagrams. [7M]

2 of 2