

Code No: **RT42022C R13**

Set No. 1

IV B.Tech II Semester Regular/Supplementary Examinations, April/May - 2019 SPECIAL ELECTRICAL MACHINES

(Electrical and Electronics Engineering)

Time: 3 hours Max. Marks: 70

Question paper consists of Part-A and Part-B Answer ALL sub questions from Part-A Answer any THREE questions from Part-B

1.	a)b)c)d)e)f)	PART-A (22 Marks) What are the applications SRM? Define pull in torque and pull out torque in stepper motor. Discuss the B-H curves of common permanent magnetic materials. Why is the PMBLDC motor called electronically commutated motor? What are the various linear synchronous motor topologies? Discuss the application of linear motors for traction drives.	[3] [4] [3] [4] [4] [4]
		$\underline{\mathbf{PART}} - \underline{\mathbf{B}} \ (3x16 = 48 \ Marks)$	
2.		Explain control of switched reluctance motor and draw the current and torque waveforms.	[16]
3.	a) b)	Discuss about single stack VR stepper Motor. Explain different configurations for switching the phase windings in stepper motor.	[8] [8]
4.	a) b)	Develop the equivalent circuit of Permanent magnet DC Motor. Explain the working principle of Permanent Magnet DC Motors.	[8] [8]
5.		Explain in detail the advantages and disadvantages of BLDC Motors over conventional DC or AC motors.	[16]
6.	a) b)	Discuss the operation principle of with Active Reaction Rail-Construction. Explain in detail the working principle of Linear Induction Motors.	[8] [8]
7.		What are the different types of AC motors are suitable for electric traction? Explain in detail.	[16]



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Set No. 2

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Time: 3 hours Max. Marks: 70

Question paper consists of Part-A and Part-B Answer ALL sub questions from Part-A Answer any THREE questions from Part-B

PART-A (22 Marks)

1.	a)	What are essential difference between Switched reluctance motor and	
		conventional reluctance motor?	[3]
	b)	What is meant by micro stepping in stepper motor? What are its advantages?	[4]
	c)	List the permanent magnet materials used in PMDC machines.	[3]
	d)	Discuss the basic configuration of BLDC Motor.	[4]
	e)	List the applications of Linear Induction Motor	[4]
	f)	What are main characteristics of traction drives?	[4]
		$\underline{\mathbf{PART-B}}\left(3x16=48Marks\right)$	
2.	a)	Explain the principle of operation of Switched reluctance motor.	[8]
	b)	Discuss about the control of Switched reluctance motor for traction type loads.	[8]
	0)	Discuss about the control of switched relactance motor for traction type loads.	[0]
3.		With neat sketches, explain the construction and principle of operation of	
		Hybrid stepping motor.	[16]
4.	a)	Write short notes on Moving coil Motors.	[8]
→.	b)	Explain the constructional details of Permanent Magnet DC Motors.	[8]
	U)	Explain the constructional details of Termanent Magnet DC Motors.	լօյ
5.	a)	Describe how the conventional DC motor is developed as Electronically	
	,	Commutated DC Motor.	[8]
	b)	Explain the Methods for reducing Torque Pulsations.	[8]
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6.		Explain in detail the construction and working principle of Linear Induction	
		Motors.	[16]
7.		What are the different types of DC motors are suitable for electric traction?	
		Explain in detail	[16]



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Set No. 3

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(Electrical and Electronics Engineering)

Time: 3 hours Max. Marks: 70

Question paper consists of Part-A and Part-B Answer ALL sub questions from Part-A Answer any THREE questions from Part-B

PART-A (22 Marks)

1.	a)	Why rotor position sensor is essential for the operation of switched reluctance	
		motor?	[3]
	b)	Mention some applications of stepper motor.	[4]
	c)	What are the advantages of PMDC motors?	[3]
	d)	List the drawbacks of surface mounted Permanent magnet DC Machines.	[4]
	e)	Write short notes on Linear synchronous motor.	[4]
	f)	What are the advantages of using AC motors over DC motors in traction	
		control?	[4]
		$\underline{\mathbf{PART-B}} (3x16 = 48 Marks)$	
2.	a)	Write short notes on power converter principle for switched reluctance motor.	[8]
	b)	Discuss the various modes of operation of SRM.	[8]
3.		Explain in detail about closed-loop control of step motor.	[16]
4.	a)	Sketch and discuss the torque-speed characteristics of a PMDC motor.	[8]
т.	b)	Derive the torque equation of PMDC motor.	[8]
	U)	Derive the torque equation of FMDe motor.	[0]
5.		From the fundamentals, discuss how the d-q analysis of BLDC Motor is	
		developed.	[16]
6.		Explain in detail the construction and working principle of Linear synchronous	
		Motors.	[16]
7.	a)	What is the selection criterion of motors for electric traction application?	[8]
	b)	Compare AC and DC traction systems.	[8]



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Set No. 4

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SPECIAL ELECTRICAL MACHINES

(Electrical and Electronics Engineering)

Time: 3 hours Max. Marks: 70

Question paper consists of Part-A and Part-B Answer ALL sub questions from Part-A Answer any THREE questions from Part-B

PART-A (22 Marks) List out the advantages of switched reluctance motor. [4] Define holding torque and detent torque in stepper motor. [3] Mention some applications of PM DC motor. [4] What are the relative merits of the brushless dc motor drives? d) [4] e) Write short notes on Linear Induction motor. [4] What are the advantages of electric traction? [3] PART-B (3x16 = 48 Marks)2. With a neat sketch, explain the Power Converter for SR Motor. Give the analysis for current and torque waveforms. [16] Explain the construction and various modes of excitation of VR stepper motor. [12] What are the advantages of VR stepper motor? [4] Explain in detail the construction and working principle of Permanent Magnet 4. DC Motors. [16] Explain the constructional details of BLDC motor with the help of neat 5. a) sketches. [8] Write short notes on theory of brushless DC motor as variable speed b) synchronous motor. [8] Explain in detail the working principle of Linear synchronous Motors. 6. [8] a) Give the analysis of Linear Induction motor in terms of electromagnetic equations. [8] 7. Explain how the single sided linear induction motor is used for traction drive applications. [16]