

Code: 9A02804

1

B. Tech IV Year II Semester (R09) Regular Examinations, March/April 2013

SPECIAL ELECTRICAL MACHINES

(Electrical & Electronics Engineering)

Time: 3 hours

Max. Marks: 70

Answer any FIVE questions
All questions carry equal marks

- 1 Draw and explain series and shunt boosters in detail.
- 2 Explain Rosenberg generator with neat diagram and draw its N-I curve.
- 3 Discuss the principle of operation of permanent magnet stepper motor with torque versus angle characteristics.
- 4 Derive the torque equation for variable reluctance stepper motor.
- 5 Discuss the various converter topologies for a 3- ϕ SRM with its merits and demerits.
- 6 Write the comparison between permanent magnet brushless DC motor and conventional DC motor.
- 7 Explain the double sided linear induction motor from rotator type IM with neat diagrams.
- 8 State the difference between conventional and electronically commutated DC motor.

Code: 9A02804

2

B. Tech IV Year II Semester (R09) Regular Examinations, March/April 2013

SPECIAL ELECTRICAL MACHINES

(Electrical & Electronics Engineering)

Time: 3 hours

Max. Marks: 70

Answer any FIVE questions
All questions carry equal marks

- 1 Explain the following with neat diagrams:
 - (a) Series booster
 - (b) Constant current booster

- 2 A 2.5 KW, 200 V metadyne generator driven by a synchronous motor at 1500 r.p.m has the following constants:
 - Control field resistance $R_f = 20\Omega$
 - Voltage constant $K_{af} = 200 \frac{V}{\text{field A}}$
 - Voltage constant $K_{qd} = K_{dq} = 100V/A$
 - Armature resistance $R_a = 5\Omega$The metadyne supplies a 20Ω resistance at a voltage of 200 V. Find the power input to the control field and power amplification for 50% compensation.

- 3 Explain the operation of 2 \emptyset hybrid step motor.

- 4 Describe the operation of variable reluctance stepper motor.

- 5 With a neat diagram, describe in detail the microprocessor based controller in switched reluctance motor.

- 6 Draw the diagram of electronic commutator. Explain the operation of the same.

- 7 Explain the principle of operation of permanent magnet brushless DC motor with neat diagram.

- 8
 - (a) Write the assumptions to be made for field analysis of DSLIM.
 - (b) Draw the DSLIM diagram.

Code: 9A02804

3

B. Tech IV Year II Semester (R09) Regular Examinations, March/April 2013

SPECIAL ELECTRICAL MACHINES

(Electrical & Electronics Engineering)

Time: 3 hours

Max. Marks: 70

Answer any FIVE questions
All questions carry equal marks

- 1 Explain the amplidyne and metadyne with neat diagram and draw its V-I curves.
- 2 Discuss the drive circuits of stepper motor in detail.
- 3 Derive the e.m.f and torque equation of permanent magnet brush less DC motor.
- 4 Draw and explain the characteristics of switched reluctance motor.
- 5 Draw and explain constant current booster in detail. Write the differences between reversible and non reversible boosters.
- 6 Explain linear induction motor for traction in detail with neat diagram.
- 7 Explain the characteristics of stepper motor.
- 8 Explain B-H loop in detail.

Code: 9A02804

4

B. Tech IV Year II Semester (R09) Regular Examinations, March/April 2013

SPECIAL ELECTRICAL MACHINES

(Electrical & Electronics Engineering)

Time: 3 hours

Max. Marks: 70

Answer any FIVE questions
All questions carry equal marks

- 1 Draw and explain reversible and shunt type boosters in detail.
- 2 Write the principle of cross field rotating machines and explain any one type of armature excited machine in detail with neat diagram.
- 3 (a) Explain torque versus stepping rate characteristics of a stepper motor.
(b) What is stepping angle? Calculate the stepping angle for a 3- ϕ 24 pole permanent magnet type stepper motor.
- 4 Explain the types of variable reluctance stepper motor in detail.
- 5 Explain the short position sensing of switched reluctance motor.
- 6 Draw the equivalent circuit of PM system with armature and write the equations used for finding the origin 'K' of the recoil line for PM without the armature.
- 7 Explain the magnetic circuit analysis of PM brushless DC motor.
- 8 The linear IM has 98 poles and a pole pitch of 50 cm. Determine the synchronous speed and vertical speed in Km/hr, if frequency is 50 Hz and slip is 0.25.
